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AREA AVERAGED FIlM FLOW EQUATIONS
PART 1: THE CONTINUITY AND MOMENTUM EQUATIONS

By

GUNOL KOCAMUSTAFAOGLULARI and NOVAK ZUBER

For

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AREA AVERAGED FILM FLOW EQUATIONS

PART I: THE CONTINUITY AND MOMENTUM EQUATIONS

by

Gunol Kocamustafaogullari and Novak Zuber

School of Mechanical Engineering
Georgia Institute of Technology
Atlanta, Georgia 30332

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Novak Zuber, Principal Investigator
Fuller E. Callaway Professor

Stothe P. Kezios, Director
School of Mechanical Engineering
A new formulation of liquid film flow is presented which is based on the "thin film" approximation and the appropriate "jump" conditions at the liquid-vapor interface. These "jump" conditions are used in deriving the space averaged, time dependent continuity and momentum equations which take into account the effects of capillary and body forces, of evaporation or condensation, of liquid injection or removal at the wall as well as the dynamic effects of the vapor phase in co-current or countercurrent flow.

Similarity criteria are derived which can be used for purpose of scaling; their significance is also discussed.

The results of the analysis show among other that evaporation has a destabilizing effect on the dynamics of the film whereas the opposite is due for condensation.
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1. INTRODUCTION

1.1 Relevance of the Problem

The flow of liquid films is a separated two-phase flow pattern of great interest to various technologies because many engineering operations and systems are greatly affected by the behavior of such films. In the aero-space technology, for example, the performance of a rocket engine cooled by a liquid film, depends on the protective effectiveness of the film. In the chemical process, nuclear reactor and power generating industries the performance of distillation and absorption plants, of condensers, boilers and evaporators, of desalination plants, of nuclear reactors etc, are greatly affected by the film because the processes of mass and heat transfer which occur in these systems, are intimately connected to fluid motion.

More recently, the developments of heat pipes and the investigations concerned with the effects of a zero-g environment, stimulated an interest in thermo-capillary phenomena and their effects on liquid film motion.

Finally, separated two phase flow regimes such as liquid films, may even be of greater interest in the future in view of the advantage which evaporation cooling offers as a mean for controlling thermal pollution of the environment.

1.2 Previous Studies

In order to predict the performance and obtain an optimal design of the systems and components listed above as well as to ensure a safe operation of some of these systems, it is necessary to have a rigorous
but realistic formulation, as well as reliable design and scaling criteria, all of them supported by accurate experimental data.

In view of the importance of this two phase flow regime, it is not surprising that a large amount of data are available on various aspects of film flows.

The references are too numerous to list them here, however, Refs. [1-16] are representative of the wide interest, numerous applications and of the various methods used in analyzing the problem.

The performance of many systems listed above is often limited by certain dynamic and thermal phenomena which occur in the film and/or at the gas-liquid interface. For example, droplet entrainment and the film dryout may put an upper limit on the performance of systems (such as rocket engines, nuclear reactors, desalination plants) which use liquid films as a method for achieving better cooling, evaporation or mass transfer.

In order to predict these operational limits it is necessary to have a realistic formulation that takes into account the physical processes which characterize the phenomenon. For liquid films in a thermal environment, such a formulation should take into account: 1) the dynamic characteristics of the liquid and vapor flows, 2) the physical processes occurring at the gas-liquid interface and 3) the effects of heat and mass transfer at the film boundaries.

Although there are numerous publications dealing with liquid films, a formulation which takes into account these three aspects of the problem is still lacking. Thus, most investigations which were concerned with dynamic aspects of the interface, were formulated for adiabatic flows and neglected the effects of mass transfer. Conversely, all formulations
concerned with thermal and mass transfer aspects of the problem did not take into account dynamic phenomena at the gas-liquid interface.

1.3 Purpose of the Paper

It appears from the foregoing that for liquid film flows there is a need for a formulation which takes into account: 1) the dynamics of liquid motion, 2) the effects of vapor motion, 3) the physical processes occurring at the gas-liquid interface and 4) the effects of heat and mass transfer at the boundaries of the liquid film.

This paper has three purposes:

1) To present a formulation which takes into account the various effects enumerated above.

2) To derive from this formulation an equation which predicts the behavior of flowing heated (or cooled) liquid films acted upon by body and thermo-capillary forces, vapor shear and with mass addition (or removal) at the boundaries.

3) To derive the relevant similarity criteria which can be used for purposes of scaling.

2. FORMULATION

2.1 The "Thin Film" Formulation

It was noted in Ref. [17] that the theory of lubrication films is the hydrodynamic analog of the shell theory, since the thickness of the film is much smaller than its lateral dimensions. Consequently, the dependence upon one of the three spatial variables can be eliminated from the hydrodynamic equations. Although the analogy was not appreciated, an approach equivalent to the shell theory has been used in many analyses
of liquid films, Refs. [6, 7, 8, 9, 10, 11] among others.

In this paper the "thin film" method will be used i.e., the continuity and the momentum equation for the liquid will be integrated across the film, Ref. [18]. However, in contrast to previous analyses, in this paper we shall take into account the "jump" conditions at the gas-liquid interface relevant to the present problem. Since the integrated, i.e., the area averaged equations depend on the end values of the integral i.e., on the "jump" conditions, it can be anticipated that the equations derived in this paper differ from those available in the literature.

2.2 Field Equations and Approximations

The physical system to be analyzed is illustrated on Figure 1.

![The Liquid Film Model](image)

**Fig. 1**

The Liquid Film Model

A liquid film flows upward and concurrently with the vapor phase.

A liquid mass flux $m_w$, enters the film through the porous wall, whereas a mass flux $m$, leaves it at the interface.

For a two-dimensional, incompressible liquid the continuity equation is
\[
\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} = 0
\]  
(1)

whereas the \(x\) and \(y\) components of the momentum equation are given respectively by:

\[
\rho \left\{ \frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} \right\} = - \frac{\partial P}{\partial x} + \mu \left( \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} \right) - \rho g \sin \theta
\]  
(2)

and

\[
\rho \left\{ \frac{\partial v}{\partial t} + u \frac{\partial v}{\partial x} + v \frac{\partial v}{\partial y} \right\} = - \frac{\partial P}{\partial y} + \mu \left( \frac{\partial^2 v}{\partial x^2} + \frac{\partial^2 v}{\partial y^2} \right) - \rho g \cos \theta
\]  
(3)

The "thin film" formulation is based on the assumption that the film thickness is small compared to the longitudinal dimension. Thus, if \(\eta_0\) denotes a typical value of the film thickness \(\eta(x, t)\), and \(L\) denotes a typical longitudinal dimension, we introduce

\[
\varepsilon = \frac{\eta_0}{L}
\]  
(4)

as a perturbation parameter.

We shall want to compare the magnitudes of the various terms in Eqs. (1, 2 and 3). For this purpose and following the boundary layer analysis, we shall introduce the dimensionless coordinates defined by

\[
x^+ = \frac{x}{L}
\]  
(5)

and

\[
y^+ = \frac{y}{\eta_0}
\]  
(6)
Introducing a reference velocity \(<u>\), the dimensionless velocity in the x direction becomes

\[ u^+ = \frac{u}{<u>} \tag{7} \]

The scale for the y component of the velocity is obtained by substituting Eqs. (5, 6 and 7), into the continuity equation, Eq. (1), thus

\[ v^+ = \frac{v}{\varepsilon<u>} \tag{8} \]

which is in agreement with the boundary layer approximation.

We turn now our attention to the definition of a dimensionless pressure. We can normalize the pressure either with respect to the dynamic pressure \(\rho<u>^2\), or with respect to an appropriate measure of viscous stresses such as \(\mu<u>/\eta_0\). Since, for thin films, it can be expected that viscous forces will be important we shall choose the latter normalization factor. To allow for the possibility that the perturbation parameter may enter into the coefficient of proportionality we set

\[ p = \frac{p}{\mu<u>^2} \varepsilon^n \eta_0 \tag{9} \]

where \(n,\) will be determined from the momentum equation.

Finally, since the motion of the gas-liquid interface has an important effect on the flow in the film, we shall normalize the time by introducing a characteristic frequency \(\omega,\) of oscillations of the interface, thus

\[ t^+ = \omega t \tag{10} \]
The momentum equation can be expressed in dimensionless form by means of Eq. (4) through Eq. (9), thus

\[
\epsilon \, \text{Re} \left\{ \frac{\partial u^+}{\partial t} + u^+ \frac{\partial u^+}{\partial x} + v^+ \frac{\partial u^+}{\partial y} \right\} =
\]

\[
- \epsilon^{1-n} \frac{\partial p^+}{\partial x} + \epsilon^2 \frac{\partial^2 u^+}{\partial x^2} + \frac{\partial^2 u^+}{\partial y^2} - \frac{\text{Re}}{\text{Fr}} \sin \theta
\]

and

\[
\epsilon^3 \text{Re} \left\{ S \frac{\partial u^+}{\partial t} + u^+ \frac{\partial u^+}{\partial x} + v^+ \frac{\partial u^+}{\partial y} \right\} =
\]

\[
- \epsilon^{1-n} \frac{\partial p^+}{\partial y} + \epsilon^4 \frac{\partial^2 u^+}{\partial x^2} + \epsilon^2 \frac{\partial^2 v^+}{\partial y^2} - \frac{\text{Re}}{\text{Fr}} \cos \theta
\]

where we have defined the Reynolds number by

\[
\text{Re} = \frac{<u>}{\nu} \eta_o
\]

the Froude number by

\[
\text{Fr} = \frac{<u>^2}{g\eta_o}
\]

and the Strouhal number by

\[
S = \frac{\omega L}{<u>}
\]
By taking the value of $n = 1$ for the exponent in Eq. (11) the pressure force will have the same order of magnitude as the viscous stress. Selecting therefore this value for $n$, Eq. (11) and Eq. (12) yield for the zeroth's order approximation, the following relations:

$$\frac{\partial P^+}{\partial x^+} = \frac{3}{2} \frac{u^+}{v^+} + \frac{Re}{Fr} \sin \theta$$  \hspace{1cm} (16)

and

$$\frac{\partial P^+}{\partial y^+} = 0$$  \hspace{1cm} (17)

which describes the primary flow.

The first order approximation is obtained from Eq. (11) and Eq. (12) by retaining only the first order terms in $\varepsilon$, thus

$$\varepsilon Re \left\{ \frac{3}{2} \frac{u^+}{v^+} + \frac{u^+}{v^+} \right\} = -\frac{\partial P^+}{\partial x^+} + \frac{3}{2} \frac{u^+}{v^+} + \frac{Re}{Fr} \sin \theta$$  \hspace{1cm} (18)

and

$$\frac{\partial P^+}{\partial y^+} = -\varepsilon \frac{Re}{Fr} \cos \theta$$  \hspace{1cm} (19)

It is noted here that Eq. (18) and Eq. (19) are equivalent to the boundary layer or hydraulic approximations.

In dimensional form Eq. (18) and Eq. (19) become:

$$\frac{\partial \rho u}{\partial t} + \frac{\partial}{\partial x} (\rho u^2) + \frac{\partial}{\partial y} (\rho uv) = -\frac{\partial P}{\partial x} + \mu \frac{\partial^2 u}{\partial y^2} - \rho \phi \sin \theta$$  \hspace{1cm} (20)
and

\[ \frac{\partial P}{\partial y} = -\gamma \cos \theta \]  

which together with the continuity equation

\[ \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} = 0 \]

describe the flow in thin liquid films.

2.3 **The "Jump" Conditions**

In order to integrate Eqs. (20, 21, and 22) across the liquid film it is necessary to consider the end values of the integrals, i.e., the boundary conditions at the liquid-solid and gas-liquid interfaces. Various aspects of the interfacial "jump" i.e. Kotchine's conditions have been considered by several researchers Refs. [5, 10, 12, 19, 20, 21, 22] among others.

In deriving the "jump" conditions for the momentum equation the main problem is to account properly, for the effects of the surface stress tensor. For a Newtonian interface, the appropriate expressions for this interfacial stress have been derived in Ref. [19], see also Refs. [20, 21]. However, to use these expressions at the present time poses a difficulty because experimental data are not available on surface shear and dilatational viscosities. Thus, although the effects of these two surface viscosities can be formally considered their effect at present, cannot be evaluated quantitatively. Consequently, in this paper we shall consider only the static effects, i.e., the effects of the surface tension.
since the values of \( \sigma \), are available.

With the surface stress expressed only in terms of the surface tension \( \sigma \), the "jump" conditions for the continuity and momentum equations become, Refs. [19, 20, 21, 22],

\[
\rho (\vec{v} - \vec{v}) \cdot \hat{n} + \rho_2 (\vec{v}_2 - \vec{v}) \cdot \hat{n}_2 = 0
\] (23)

and

\[
\rho (\vec{v} - \vec{v}) \cdot \hat{n} \vec{v} = \vec{\Pi} \cdot \hat{n} + \rho_2 (\vec{v}_2 - \vec{v}) \cdot \hat{n}_2 \vec{v}_2 - \vec{\Pi}_2 \cdot \hat{n}_2 = \frac{\sigma}{R} \hat{n} - \frac{\partial \sigma}{\partial s} \hat{t}
\] (24)

where: \( \hat{n} \) and \( \hat{n}_2 \) are unit normal vectors at the interface directed outward from the liquid and from the vapor (phase two) respectively and \( \hat{t} \), is the unit tangent vector at the interface. According to Figure 1, it follows that:

\[
\hat{n} = \hat{n}_2 = -i \sin \beta + j \cos \beta
\] (25)

and

\[
\hat{t} = i \cos \beta + j \sin \beta
\] (26)

In Eq. (24), \( s \) is the arc-length along the interface; \( 1/R \) is the curvature of the gas-liquid interface, given by

\[
\frac{1}{R} = -\frac{\frac{\partial^2 n}{\partial x^2}}{\left(1 + (\frac{\partial n}{\partial x})^2\right)^{3/2}}
\] (27)

and \( \Pi_{jk} \) and \( \Pi_{2jk} \) are the stress tensors for the liquid and the vapor given
respectively by

\[ \Pi_{jk} = -P \delta_{jk} + \tau_{jk} \]  

(28)

and

\[ \Pi_{2jk} = -P \delta_{jk} + \tau_{2jk} \]  

(29)

The "jump" conditions given by Eqs. (23 and 24) will be now simplified in view of the "thin film" approximation.

Defining by \( \dot{m} \), and \( \dot{m}_2 \), the mass flux outward from the liquid and the vapor, it follows that

\[ \dot{m} = \rho (\vec{v} - \hat{V}) \cdot \hat{n} \]  

(30)

\[ \dot{m}_2 = \rho_2 (\vec{v}_2 - \hat{V}) \cdot \hat{n}_2 \]  

(31)

The conservation of mass at the interface i.e., Eq. (23), requires that

\[ m + m_2 = 0 \]  

(32)

For a two dimensional flow the velocities of the liquid and of the interface can be expressed as

\[ \vec{v} = i u + j v \]  

(33)

\[ \vec{V} = i U + j V \]  

(34)

Using these two equations together with Eqs. (25, 30 and 32) it can be easily shown Refs. [12, 13], that the y components of the liquid and interface velocities are related by:
\[ \mathbf{v}_i - \mathbf{v} = \frac{\dot{m}}{\rho} \left[ 1 + \left( \frac{\partial n}{\partial x} \right)^2 \right]^{-1/2} \]  \hfill (35)

The assumption of no "slip" at the interface i.e.,

\[ \mathbf{v}_i \cdot \hat{t} = \mathbf{\hat{V}} \cdot \hat{t} \]  \hfill (36)

together with Eqs. (34, 33 and 26) leads to the relation between the x components of the velocities, thus

\[ u_i - U = - \frac{\dot{m}}{\rho} \frac{\partial n}{\partial x} \left[ 1 + \left( \frac{\partial n}{\partial x} \right)^2 \right]^{-1/2} \]  \hfill (37)

Since the "thin film" approximation implies that

\[ \frac{\partial n}{\partial x} - \varepsilon < 1.0 \]  \hfill (38)

the second order, i.e., \( \varepsilon^2 \), terms can be neglected in Eqs. (37 and 35). Thus at the interface, the velocity components are given by:

\[ \mathbf{v}_i - \left( \frac{\partial n}{\partial t} + u_i \frac{\partial n}{\partial x} \right) = \frac{\dot{m}}{\rho} \]  \hfill (39)

and

\[ u_i - U = - \frac{\dot{m}}{\rho} \frac{\partial n}{\partial x} \]  \hfill (40)

where we have expressed the y component of the interface velocity by

\[ v = \frac{\partial n}{\partial t} + u_i \frac{\partial n}{\partial x} \]  \hfill (41)

We note that in absence of mass transfer, \( \dot{m} \), Eqs. (39 and 40) reduce to
the standard boundary condition for the velocity at a moving interface
Refs. [5, 23].

Turning now our attention to the "jump" condition for the momentum
equations, we resolve Eq. (24) into the x and y components utilizing Eqs.
(34, 33, 32, 31, 30, 29, 28, 26 and 25) and obtain respectively

\[ \left( \tau_{2xy} - \tau_{xy} + \frac{\partial \sigma}{\partial S} + (\tau_{xx} - \tau_{2xy} + \rho_2 - \rho \right) 
\]

\[ = \sigma \frac{\partial^2 \eta/\partial x^2}{\{1 + (\partial \eta/\partial x)^2\}^{1/2}} + \frac{m}{\rho_2} \frac{\Delta \rho}{\rho} \frac{\partial \eta}{\partial x} = 0 \]

and

\[ \left( \tau_{2yy} - \tau_{yy} + \rho - \rho_2 + \frac{\partial^2 \eta/\partial x^2}{\{1 + (\partial \eta/\partial x)^2\}^{1/2}} \right) \]

\[ = -\frac{m^2}{\rho} \frac{\Delta \rho}{\rho} + \left( \tau_{xy} - \tau_{2xy} + \frac{\partial \sigma}{\partial S} \right) \frac{\partial \eta}{\partial x} = 0 \]

where

\[ \tau_{xx} = 2\mu \frac{\partial u}{\partial x} \]

\[ \tau_{yy} = 2\mu \frac{\partial v}{\partial y} \]

\[ \tau_{xy} = \mu \left( \frac{\partial u}{\partial y} + \frac{\partial v}{\partial x} \right) \]
It was seen in the preceding section that in the momentum equation, the normal viscous stresses are of the order of $\varepsilon^2$ or higher; they were neglected therefore in the "thin film" approximation. In order to be consistent, the same approximation must be introduced in the "jump" conditions.

Therefore, neglecting the normal stresses as well as the second order terms in $\varepsilon$, i.e. $(\partial \eta / \partial x)^2$ in Eqs. (42 and 43) we obtain

$$\tau_{2xy} - \tau_{xy} + \frac{3\sigma}{\alpha} + \left[ \frac{P_2 - P - \sigma \frac{\partial \eta}{\partial x^2}}{\rho} + \frac{\dot{m}}{\rho^2} \frac{\Delta \rho}{\partial x} \right] \frac{\partial \eta}{\partial x} = 0 \quad (47)$$

and

$$P - P_2 + \sigma \frac{\partial \eta}{\partial x^2} - \frac{\dot{m}}{\rho} \frac{\Delta \rho}{\rho^2} + \left[ \tau_{xy} - \tau_{2xy} + \frac{2\sigma}{\partial s} \frac{\partial \eta}{\partial x} \right] \frac{\partial \eta}{\partial x} = 0 \quad (48)$$

Substituting Eq. (48) in Eq. (47) and neglecting the second order terms in $\varepsilon$, results in

$$\tau_{2xy} - \tau_{xy} + \frac{\partial \sigma}{\partial s} = 0 \quad (49)$$

whereas, Eq. (48) in view of Eq. (49), becomes

$$P_2 - P - \sigma \frac{\partial \eta}{\partial x^2} + \frac{\dot{m}}{\rho} \frac{\Delta \rho}{\rho^2} - 2 \frac{\partial \sigma}{\partial s} \frac{\partial \eta}{\partial x} = 0 \quad (50)$$

Eqs. (49 and 50) specify the conditions which the shear stress and pressure must satisfy at the gas-liquid interface. We note that in absence of mass transfer, these two equations reduce to standard expressions, Refs. [5, 23]. Furthermore, since for evaporation $\dot{m}$ is positive, Eq. (50) shows that
vaporization gives rise to a vapor thrust directed from the vapor towards the liquid.

The "jump" conditions given by Eqs. (50, 49, 40 and 39), together with the field equations given by Eqs. (22, 21 and 20) formulate the liquid film flow problem consistent with the "thin film" approximation.

3. DERIVATION

3.1 Area Averages

In this section we shall integrate the continuity and momentum equation across the liquid film obtaining thereby the "thin film" model Ref. (18). For this purpose we shall define the area averaged value of a property F, by

\[ <F> = \frac{1}{\eta(x,t)} \int_0^{\eta(x,t)} F \ dy \] (51)

In integrating the momentum and the continuity equations across the liquid film we shall make frequent use of Leibnitz formula which for the purpose of this paper, can be expressed as:

\[ \int_0^{\eta(x,t)} \frac{\partial F}{\partial \xi} \ dy = \frac{\partial}{\partial \xi} \left\{ \int_0^{\eta(x,t)} Fdy \right\} - F(\eta) \frac{\partial \eta}{\partial \xi} \] (52)

where \( \xi \) denotes either the time \( t \), or the longitudinal direction \( x \). By means of Eq. (51), this relation can be also expressed in terms of the area averaged \( <F> \), thus

\[ \int_0^{\eta(x,t)} \frac{\partial F}{\partial \xi} \ dy = \frac{\partial}{\partial \xi} \{ \eta(x,t) <F(x,t)> \} - F(\eta) \frac{\partial \eta}{\partial \xi} \] (53)
Finally, in what follows we shall want to express the average value of \( F \) squared, i.e., of \( <F^2> \), in terms of the square of the average value of \( F \), i.e., of \( <F>^2 \). Such a relation is obtained by recalling the definition of the covariant given by:

\[
<F^2> = <F>^2 + \text{cov}(F^2)
\]  

(54)

In what follows, Eqs. (53 and 54) will be used together with the appropriate boundary and "jump" conditions, to integrate the momentum and continuity equations.

3.2 The Continuity Equation

The continuity equation to be integrated across the liquid film is given by Eq. (22). For a film with liquid injection through a porous wall, the boundary conditions for the velocity at such a wall are given by:

\[
\text{at } y = 0 : u = 0 \quad v = \frac{m_w}{\rho}
\]  

(55)

The "jump" conditions at the gas-liquid interface, i.e., at \( y = \eta(x,t) \) are given by Eqs. (39 and 40).

Integrating Eq. (22) across the liquid film and in view of Eqs. (55, 54, 40 and 39) the area averaged, i.e., the one-dimensional continuity equation for the liquid film becomes:

\[
\frac{\partial \eta}{\partial t} + \frac{\partial}{\partial x} (\eta \langle u \rangle) = - \frac{\dot{m} - m_w}{\rho} \tag{56}
\]

We note that in absence of mass addition and removal Eq. (56), reduces to the well known continuity equation for long waves, Refs. (23, 24).
3.3 The Momentum Equation

The momentum equation to be integrated across the liquid film is given by Eqs. (20 and 21). The boundary conditions for the velocity at the solid-liquid and gas-liquid interfaces are given by Eqs. (39, 40 and 55). The "jump" conditions for the shear stress and pressure are given by Eqs. (49 and 50).

Integrating Eq. (20) and in view of (Eqs. 53 and 39), the area averaged, i.e., the one-dimensional momentum equation for the liquid film can be expressed as:

\[
\frac{\partial}{\partial t} \{ \eta <pu> \} + \frac{\partial}{\partial x} \{ \eta <u^2> \} + u_i \cdot \mathbf{m} - \rho u_i \{ u_i - u \} \frac{\partial \eta}{\partial x} =
\]

\[
= - \frac{\partial}{\partial x} \{ \eta <P> \} + \mu \frac{\partial u}{\partial y} \Big|_i - \mu \frac{\partial u}{\partial y} \Big|_w + P_i \frac{\partial \eta}{\partial x} - g \rho \eta \sin \theta
\]

utilizing Eq. (40), neglecting the higher order terms in \(\partial \eta/\partial x\), and assuming that the density of the liquid does not change appreciably across the film, we get

\[
\frac{\partial}{\partial t} \{ \eta \rho <u> \} + \frac{\partial}{\partial x} \{ \eta \rho <u^2> \} + u_i \cdot \mathbf{m}
\]

\[
= - \frac{\partial}{\partial x} \{ \eta <P> \} + \tau_i - \tau_w + P_i \frac{\partial \eta}{\partial x} - g \rho \eta \sin \theta
\]

where \(\tau_i\) and \(\tau_w\) are the liquid shear stresses at the interface and at the wall.

The average pressure in liquid \(<P>\), and the liquid pressure at the
interface $P_1$, can be found by integrating Eq. (21), thus

$$<P> - P_1 = \frac{1}{2} g_\eta \cos \theta$$  \hspace{1cm} (59)$$

The liquid shear stress at the interface $\tau_1$ and the pressure in the liquid at the interface $P_1$, can be expressed in terms of the flow in the vapor phase by means of the "jump" conditions, Eqs. (49, 50). Substituting Eqs. (59, 50 and 49) into Eq. (58) we get

$$\frac{\partial}{\partial t} \{\eta \langle u \rangle \} + \frac{\partial}{\partial x} \{\eta \langle u^2 \rangle \} + u_1 \cdot m = - \eta \frac{\partial}{\partial x} \{ -2 \frac{\partial \eta}{\partial \eta} \frac{\partial \eta}{\partial x} + P_{21} - \sigma \frac{\partial \eta}{\partial x}^2 + \frac{m^2}{\rho_2} \frac{\Delta \rho}{\rho_2} \}$$

$$+ \tau_{21} - \tau_{w} + \frac{\partial \sigma}{\partial s} \cdot g_{\eta} \frac{\partial \eta}{\partial x} \cos \theta - g_{\eta} \sin \theta \frac{\partial}{\partial x} \{ \eta \cos \langle u^2 \rangle \}$$

where we have used the definition of the covariant given by Eq. (54) and where $\tau_{21}$, is the vapor shear stress evaluated at the interface.

We note, that if we neglect the effects of the a) vapor pressure, b) vapor shear c) surface tension, d) mass transfer and e) velocity distribution, then Eq. (60) reduces to the well known momentum equation for channel flow, Ref. [24].

By expanding the left hand side of Eq. (60) and using the continuity equation Eq. (56) we get the equation of motion for the liquid film:

$$\rho_\eta \{ \frac{\partial \langle u \rangle}{\partial t} + \langle u \rangle \frac{\partial \langle u \rangle}{\partial x} \} + \langle u \rangle m + \langle u \rangle \dot{m} = - \eta \frac{\partial}{\partial x} \{ P_{21} - \sigma \frac{\partial \eta}{\partial x}^2 + $$

$$\frac{m^2}{\rho_2} \frac{\Delta \rho}{\rho_2} - 2 \frac{\partial \eta}{\partial s} \frac{\partial \eta}{\partial x} + g_{\eta} \cos \theta \} - g_{\eta} \sin \theta + \tau_{21} - \tau_{w} + \frac{\partial \sigma}{\partial s} - \frac{\partial}{\partial x} \{ \eta \cos \langle u^2 \rangle \}$$

(61)
It can be seen from Eqs. (60 and 61) that the evaporation affects the flow in the film in two ways. It reduces the effective pressure distribution along the channel and it acts as a sink for the momentum.

4. DISCUSSION

4.1 Effects of Various Parameters

4.1.1 The Effect of Flow Regimes

The "thin film" model is formulated in terms of the continuity equation, Eq. (56), and the momentum equation, Eq. (60), i.e., Eq. (61), which can be used to evaluate the effects of various parameters on the dynamic characteristics of the film.

Thus, the effect of the liquid flow regime is reflected in the wall shear stress $\tau_w$, the covariant term and the two momentum sink terms in Eq. (61). While the importance of the velocity distribution in determining the values of $\tau_w$, and of the covariant term are well known, Ref. (25), it can be seen from Eq. (61) that the effects of mass transfer on the film flow dynamics depend also on the velocity profile.

For example, in a laminar flow regime, the effect of the momentum sink amounts to approximately

$$\{u_i - <u>\} \cdot \dot{m} \approx \frac{1}{2} <u> \cdot \dot{m}$$

(62)

whereas for a turbulent, i.e., a flat profile the contribution of this term is almost nil.

4.1.2 Thermo-Capillary Effects

The effects of surface tension are accounted for by two terms in Eq. (61), one affects the pressure distribution the other the shear.
The importance of these two terms will depend on the particular application. For example, it is well known that for heat pipe application, the thermo-capillary effects are most important.

4.1.3 The Effect of the Vapor Phase

It can be seen from Eq. (61) that the motion of the vapor phase influences the motion of the liquid through two terms: the pressure gradient and the vapor shear stress at the interface. In fact, for an upward flowing film the liquid flow is due to the action of the vapor only.

4.1.4 The Effects of Heat and Mass Transfer

Of particular interest is to evaluate the effects of heat and mass transfer on the liquid film. It was noted already that when \( \dot{m} \) is positive as in evaporation, the effect of mass transfer is to reduce the pressure distribution as well as to reduce the momentum, i.e., it has an effect of a momentum sink. In order to determine more precisely this effect, it is necessary to consider in more detail the mass flow \( \dot{m} \), in Eqs. (56 and 61).

By examining the continuity equation, i.e., Eq. (56) it can be seen that the mass flux \( \dot{m} \) acts as a sink, indeed it plays the same role as the sink (or source) terms in the continuity equations of chemically reacting mixtures. Whereas in chemically reacting mixtures, the sinks (or sources) are specified by appropriate constitutive equations of chemical kinetics, in two phase flow they are specified the appropriate constitutive equations of phase change, i.e., of evaporation or condensation, Refs. [18, 26, 27, 28]. Indeed, it was shown in Ref. [18] that the constitutive equation of evaporation a) depends on the flow regime and b) determines
the thermodynamic non-equilibrium of the two-phase mixture.

For example in the present problem, the expression for \( \dot{m} \), will depend on the particular application. Thus, it will have a different form depending on whether the evaporation from the liquid film is effected by exposure to hot gases (as in rocket engines), or by decreasing the system pressure (as in flash evaporators), or by heat transfer through the liquid film (as in boilers, evaporators or nuclear reactors). Let us consider briefly this last application.

The simplest expression for the constitutive equation of evaporation can be obtained by assuming that the two phase mixture is in thermodynamic equilibrium. For such a two-phase system \( \dot{m} \), can be obtained from an energy balance, Ref. [18], thus

\[
\Delta h_{fg} \dot{m} = q_w \tag{63}
\]

where \( \Delta h_{fg} \) is the latent heat of vaporization and \( q_w \) is the heat flux at the solid wall. Assuming for simplicity, that the heat flux through the liquid film is by conduction only, we obtain from Eq. (63) the expression for \( \dot{m} \), thus

\[
\dot{m} = \frac{k}{\Delta h_{fg}} \frac{(T_w - T_s)}{\eta} \tag{64}
\]

where \( T_w \) and \( T_s \) are the wall and saturation temperatures, and \( k \) is the coefficient of thermal conductivity.

Defining the convected derivatives by

\[
\frac{D<\omega>}{Dt} = \frac{\partial<\omega>}{\partial t} + <u> \frac{\partial<\omega>}{\partial x} \tag{65}
\]
and substituting Eq. (64) in Eq. (61) we obtain the following expression

for the equation of motion of a liquid film evaporating from a heated surface:

\[
\rho n \frac{D\langle u_x \rangle}{Dt} + \langle u_x \rangle \frac{k \Delta T}{\Delta s_{fg}} \frac{1}{n} - \eta \frac{\partial}{\partial x} \left( P_{21} - \sigma \frac{\partial^2 n}{\partial s^2} \right) - 2 \sigma \frac{\partial n}{\partial s} + g \rho n \cos \theta
\]

(66)

\[
- \eta \frac{\partial}{\partial x} \left( \frac{k}{\Delta s_{fg}} \frac{\Delta T}{\eta} \frac{\Delta \rho}{\rho \rho_2} \right) + \tau_{2i} - \tau_w + \frac{\partial g}{\partial s} - g \rho n \sin \theta - \frac{3}{\partial x} \left( \rho n \text{ Cov} (u^2) \right)
\]

With reference to this equation, we can make several important observations. First, we note that for evaporating films \( n \) decreases. Consequently, the effects of inertia and gravitational forces become less and less important, whereas those due to evaporation become dominant. Second, since the gradient of \( n \), i.e., \( \partial n/\partial x \), is negative for evaporating films, the evaporation thrust acts in the opposite direction to the vapor shear \( \tau_{2i} \). Consequently whether in upward or downward flow, the evaporation thrust can induce an interruption of the liquid flow which results in a local dryout.

Note, that this dryout is not brought about by the total evaporation of the film, but it can occur with a finite film thickness because of the dynamic effects in the film and at its interface.

We close by observing that because the liquid dryout can impose an operating limit on nuclear reactors, evaporators, desalination plants etc, it is one of the most important (unresolved) problems in the nuclear reactor and chemical process industries. This and other dynamic problems, based on Eqs. (66 and 56), will be treated as a separate paper.
4.2. Scaling Criteria

4.2.1 Continuity Equation - Dimensionless Form

For design of equipment as well as for the planning of experiments it is necessary to have design and scaling criteria. In this section we shall derive such criteria for liquid film flows.

Introducing the characteristic scaling parameters given by Eqs. (4, 5, 6, 7, 9 and 10) into the area averaged continuity equation, Eq. (56), we obtain

\[ \frac{\partial \eta}{\partial t} + \frac{\partial}{\partial x} \left( \eta <u> \right) = -N_{Pch} + N_{Sup} \]  

(67)

where we defined the Strouhal number by

\[ S = \frac{\omega L}{<u>} \]  

(68)

The Phase Change number, by

\[ N_{Pch} = \frac{\dot{m}}{\rho \eta_o} \frac{L}{<u>} \]  

(69)

and the Supply number, by

\[ N_{Sup} = \frac{\dot{m}}{\rho \eta_o} \frac{L}{<u>} \]  

(70)

Since the significance of the Strouhal number is well known (see Ref. [17] for example), no further comment is needed here. However, we shall discuss the relevance of the Phase Change number since it is one of the most important scaling parameters for two phase flow, Refs. [18, 26, 27, 28].

We note that the "frequency of phase change" \( \Omega \), defined here by

\[ \Omega = \frac{\dot{m}}{\rho \eta_o} \]  

(71)
scales the rate of phase change Ref. [26]. Indeed, it has the same meaning as the reaction frequency in chemical kinetics. The ratio $L/\langle u \rangle$, scales the residence time of a particle in the film. We can express therefore the Phase Change number as:

$$N_{Pch} = \Omega \frac{L}{\langle u \rangle} \quad (72)$$

Expressed in this form, i.e., as the product of the characteristic frequency and of the residence time, the Phase Change number is of a similar form to the Damköhler first group, Ref. [29], which is one of the most important similarity group used in scaling chemical reactors and rocket engines. It can be expected therefore, that for film flows, the Phase Change number will play the same role as Damköhler first group in chemically reacting systems.

In fact, the equality of the Phase Change number in two different systems ensures that the phase change has progressed equally in both. If this is not satisfied, the dynamic conditions in the two systems will not be similar, since the phase change in one would have progressed further than in the other.

The significance of the Supply number given by Eq. (70), is similar to that of the Phase Change number.

4.2.2 Momentum Equation-Dimensionless Form

Introducing the scaling parameters given by Eqs. (4, 5, 6, 7, 9 and 10) into the area averaged momentum equation, Eq. (60), we obtain:

$$\varepsilon \text{Re} \left\{ S \frac{\partial}{\partial t^+} [\eta^+ \langle u \rangle^+] \frac{\partial}{\partial x^+} [\eta^+ \langle u \rangle^+^2] + N_{Pch} u_{+1} \right\} =$$
It can be seen that in addition to the Reynolds, Strouhal, Froude and Phase Change numbers which were introduced previously by Eqs. (13, 15, 14, 69, 70) respectively, Eq. (73) introduces additional dimensionless groups given below:

The Weber number

\[ \text{We} = \frac{\rho n_{\infty} \langle u^2 \rangle}{\sigma} \]  

(74)

The Density Ratio group

\[ N_p = \frac{\rho - \rho_2}{\rho_2} \]  

(75)

The Pressure Ratio group

\[ N_p = \frac{P_{2i}}{P_{1i}} \]  

(76)

The Shear Ratio group

\[ N_\tau = \frac{\tau_{2i}}{\tau_{w}} \]  

(77)
The Friction Factor for the liquid defined by:

\[ f = \frac{t}{\rho \langle u \rangle^2} \]  

and finally, the film thickness group

\[ \varepsilon = \frac{\eta_0}{L} \]  

We note here that the exponent of \( \varepsilon \), which multiplies the Phase Change number, depends on the mass flux \( m \), i.e., on the particular application. The values of \( \varepsilon \) and of which appear in Eq. (73) are valid only if \( m \) is a constant independent of \( n \).

It is evident from Eq. (73) that in view of so many similarity groups, an exact scaling of two systems cannot be achieved in practice. However, for different applications not all groups will have the same importance. Consequently, Eq. (73) can be used to determine the importance of the various groups and select the appropriate scaling parameters.

5. CONCLUSIONS

1. The liquid film flow problem was formulated based on the "thin film" approximation and on the appropriate "jump", i.e., Kotchine's conditions.
2. From this formulation the area averaged continuity and momentum equations were derived which describe the dynamics of liquid films and take into account the effects of a) body and thermo-capillary forces, b) shear and pressure forces of the flowing vapor phase, c) mass addition and/or removal at the solid boundary as well as at the gas-liquid interface, d) heat flux at the boundaries, and e) flow regimes.
3. The importance of various processes and parameters was discussed. It was shown in particular that the evaporation thrust can interrupt the flow of the liquid and induce a local dryout.

4. The equation in their dimensionless form were used to obtain similarity groups. The significance of these groups was discussed and in particular, that of the Phase Change number. It was noted that this number is one of the most important scaling parameter.

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NOMENCLATURE

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<thead>
<tr>
<th>Symbol</th>
<th>Description</th>
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<tbody>
<tr>
<td>Fr</td>
<td>Froude number, defined by Eq. (14)</td>
</tr>
<tr>
<td>f</td>
<td>wall friction factor</td>
</tr>
<tr>
<td>g</td>
<td>gravitational acceleration</td>
</tr>
<tr>
<td>k</td>
<td>thermal conductivity of the liquid</td>
</tr>
<tr>
<td>L</td>
<td>characteristic length scale in the main flow direction</td>
</tr>
<tr>
<td>\dot{m}</td>
<td>interfacial mass transfer rate per unit area</td>
</tr>
<tr>
<td>\dot{m}_w</td>
<td>mass transfer rate at the solid boundary per unit area</td>
</tr>
<tr>
<td>N_{Pch}</td>
<td>Phase Change number, defined by Eq. (69)</td>
</tr>
<tr>
<td>N_{Sub}</td>
<td>Mass Supply number, defined by Eq. (70)</td>
</tr>
<tr>
<td>N_p</td>
<td>density ratio, defined by Eq. (75)</td>
</tr>
<tr>
<td>\hat{n}</td>
<td>unit normal vector at the interface</td>
</tr>
<tr>
<td>P</td>
<td>pressure</td>
</tr>
<tr>
<td>q_w</td>
<td>wall heat transfer</td>
</tr>
<tr>
<td>R</td>
<td>radius of curvature at the interface</td>
</tr>
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</table>
Re  Reynolds number, defined by Eq. (13)
S  Strouhal number, defined by Eq. (15)
s  arc length along the interface
Tw  wall temperature
Ts  saturation temperature
\( \hat{t} \)  unit tangent vector at the interface
\( \langle u \rangle \)  velocity scaling parameter in the x-direction
u  liquid velocity component in the x-direction
v  liquid velocity component in the y-direction
x  co-ordinate in the main flow direction
y  co-ordinate in the lateral direction
We  Weber number, defined by Eq. (74)
\( \beta \)  angle defined on Figure 1.
\( \Delta \)  difference of
\( \Delta H_{fg} \)  heat of vaporization
\( \eta \)  instantaneous film thickness
\( \eta_0 \)  mean film thickness
\( \Theta \)  inclination angle of the surface, defined on Figure 1.
\( \mu \)  dynamic viscosity of the liquid phase
\( \nu \)  kinematic viscosity of the liquid phase
\( \rho \)  density of the liquid phase
\( \rho_2 \)  density of the gas phase
\( \sigma \)  surface tension
\( \epsilon \)  perturbation parameter, defined by Eq. (4)
\( \Pi \)  total stress tensor, defined by Eq. (28)
\( \tau \)  shearing stress
\( \omega \)  interface frequency
$U$ interface velocity component in the x direction

$V$ interface velocity component in the y direction

**Superscripts:**

$(\cdot)^+$ dimensionless quantity

**Subscripts:**

$(\cdot)_2$ quantity belong to gas phase

$(\cdot)_i$ quantity evaluated at the interface

**Averages:**

$\langle \cdot \rangle$ average with respect to cross sectional area of the liquid.
REFERENCES


ANALYSIS OF POOL FILM BOILING

A THESIS

Presented to

The Faculty of the Graduate Division

By

Jean-Claude Moureau

In Partial Fulfillment

of the Requirements for the Degree

Master of Science

in Mechanical Engineering

Georgia Institute of Technology

December, 1972
ANALYSIS
OF
POOL FILM BOILING

Approved:
Chairman, Dr. Novak Zuban
Dr. Stothe P. Kezios
Dr. George M. Rentzeras
Date Approved by Chairman: [UN. 21, 1972]
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<tr>
<td>$\beta$</td>
<td>growth coefficient</td>
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<td>$f$</td>
<td>frequency of bubble release</td>
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<td>Symbol</td>
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<tr>
<td>g</td>
<td>acceleration of gravity</td>
</tr>
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<td>$h_c$</td>
<td>heat transfer coefficient when radiation is not considered</td>
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<td>i</td>
<td>complex number $= \sqrt{-1}$</td>
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**Capital Letters**

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<td>$G_1$</td>
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<td>P</td>
<td>pressure</td>
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<td>$R_a$</td>
<td>radius of curvature</td>
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<tr>
<td>$R_b$</td>
<td>radius of curvature</td>
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</table>
S  area
T  temperature
V_l  radial vapor velocity

Subscripts
l  lower fluid (vapor)
2  upper fluid (liquid)
av  average
b  bubble
c  critical
m or max  maximum
min  minimum
o  constant value
r  radiative
tot  total
w  at the wall
x,z  components in the x,z directions

Superscripts
.  per unit time
·  perturbed term
+  non-dimensional group
SUMMARY

The purpose of this thesis is threefold. First, to explain the change of boiling pattern occurring at high pressures in pool film boiling. Secondly, to include in the existing theories of film boiling from horizontal flat surfaces the effect of the mass transfer between the vapor and liquid phases. Thirdly, to extend the usual two-dimensional approach by considering the three-dimensional case.

The stability analysis of waves at the interface of two superposed fluids, known as the Rayleigh-Taylor stability analysis, is modified to take into account the mass transfer between the two heated fluids and their depths. It is shown that the vaporization at the interface has a stabilizing effect on the vapor film. It is concluded that the changes of flow pattern, that is, from vapor bubbles to vapor sheets, which were observed by several investigators of film boiling at high pressures, are due to this stabilizing effect. In particular, this change of flow regime occurs when the vapor thrust number (defined herein) equals unity.

The stability analysis is then used to derive expressions for computing critical and most dangerous wavelengths, bubble breakoff diameters and frequencies of bubble release.

Finally, equations are derived which can be used to determine the minimum heat flux and the heat transfer coefficient in pool film boiling from flat surfaces.

It is shown that all the results predicted by the present
analysis are in good agreement with the experimental data available in the literature.
CHAPTER I

INTRODUCTION

During the last two decades boiling phenomena have received much significant attention. In pool boiling different regimes have been established: nucleate, transition and film boiling. At the present time, each of these regions has been amply described and various models have been presented which correlate satisfactorily most of the experimental results.

However, a number of unsolved problems remain. Among these is the following: in the case of film boiling at high pressure an important change in the flow pattern is observed when the heat flux from the heating surface is increased. At pressures approaching the critical, the thin vapor film covering the surface and from which vapor bubbles are released grows suddenly as the heat flux is increased; a vapor sheet rises and covers the heater, while the regular pattern of bubble release disappears.

Although the photographs of Grigull and Abadzic [1] and Abadzic and Goldstein [2] exhibit very well this variation from the characteristic regularly bubbling vapor film to a large vapor blanket, the reason for this change of flow regime is not known.

One realizes that this vapor sheet occurs at high heat fluxes inducing an important interfacial evaporation. Therefore, it appears that an appropriate analysis of the phenomenon should take the inter-
facial mass transfer effects into account.

Nevertheless, in the literature these effects were not considered or partly neglected.

One of the most often used analysis of film boiling is Zuber's prediction [3] of the minimum heat flux. This derivation is based on the purely hydrodynamic instability of a liquid vapor interface known as the Rayleigh Taylor instability.

The extension of this model to the film boiling region has been done by Berenson [4]. Although he considers a mass flow parallel to the horizontal heating surface and contributing to the growth of the bubbles, Berenson neglects the mass transfer effects when he determines the locations of the prominences which will grow and depart as bubbles; indeed he uses the most unstable wavelength resulting from the Rayleigh Taylor instability analysis. Furthermore, the limits of validity of the predicted film boiling heat transfer coefficient are not well established.

The purpose of this thesis is to introduce the mass transfer terms in a slightly modified Rayleigh Taylor instability analysis in order to explain the change of boiling pattern at high pressure described above. The influence of these interfacial mass transfer terms on the minimum heat flux and the film boiling heat transfer coefficient is also calculated.

Rankin [5] was one of the first to introduce the mass transfer terms into the stability analysis. He concludes that, in the case of vapor below a colder liquid, there is damping of the interfacial wave due to the mass transfer.
As Zuber [6] emphasizes it "Whereas the vaporization at the interface has a destabilizing effect on liquid film, it has a stabilizing effect on vapor film."

In a recent paper, Hsieh [7] arrives at the same conclusion. The application of Hsieh's study to film boiling done by Dhir and Lienhard indicates that, at low pressures, the heat and mass transfer do not influence the flow pattern. However, that work does not give any criterion for the changes of configuration occurring at high pressures which are observed in experiments. Furthermore, it presents a two-dimensional formulation.

As noted by Zuber [3] the two-dimensional approach of the problem was an assumption which should be checked. Hosler and Westwater [8] write that in this problem "a confusing choice of equations arises because of uncertainties in the derivation. Can a two-dimensional model be used or must it be three-dimensional?" Further on the following questions are raised: "Are the bubbles released with a diameter equal to a half wavelength, or is the factor something else? Is the average wavelength the critical value or the most dangerous value? What is the velocity of a bubble leaving the interface?"

In this thesis, a three-dimensional stability analysis of the interface between two fluids of finite depths under the influence of a temperature gradient is presented. A criterion for the change of configuration of film boiling at high pressures is also derived. Then, the results are applied to film boiling from a horizontal flat surface to predict the bubbles diameters at breakoff and their frequency of release. Finally, expressions for the minimum flux and pool film
boiling heat transfer coefficient are obtained.
CHAPTER II

WAVE ANALYSIS

2.1 Definition of the Problem

This analysis will determine the behavior of a flat interface separating two superposed fluids of different densities, subject to the action of small disturbances. The solution of this problem in the two-dimensional approximation can be found in Lamb [9]. The real three-dimensional case has been treated briefly by Maxwell [10].

The model considered is as follows: The underlying fluid (designated by the index 1) has a depth $\delta_1$ measured from a flat plate and a velocity $\dot{v}_1$ while the upper fluid (index 2) has a depth $\delta_2$ and a velocity $\dot{v}_2$. The (x-z) plane is taken as the common boundary of the two undisturbed fluids and the y-axis is directed vertically upwards as shown in Figure 1. For this model, two continuity, two momentum and two energy field equations (one for each fluid), and three jump conditions at the interface are written. This will lead to a general expression of the wave velocity which is introduced in the following chapter into a Rayleigh-Taylor instability analysis applied to pool film boiling.

2.2 Determination of the Potentials

The continuity equations of the two phases reduce for incompressible fluids in irrotational flows to the Laplace's equations:
Figure 1. Interfacial Wave Between Two Fluids.
where $\phi_1$ and $\phi_2$ are the potentials of the velocities

\[ \nabla^2 \phi_1 = 0 \] (1)

and

\[ \nabla^2 \phi_2 = 0 \] (2)

It is assumed that irrotational flows exist and the concepts of potential flow theory are used. Some additional restrictions are attached to this presentation; to see these, let us compare the order of magnitude of the various terms of the momentum equation of fluid one (the same could be done for the other fluid)

\[ \rho_1 \frac{\partial \mathbf{v}_1}{\partial t} + \rho_1 \mathbf{v}_1 \cdot \nabla \mathbf{v}_1 = -\nabla p_1 + \mu_1 \nabla^2 \mathbf{v}_1 + \rho_1 \mathbf{g} \] (5)

When the interface is under the influence of small irregularities it
is displaced and waves are formed. Using the wavelength $\lambda$ as a scaling factor for the length, $\omega^{-1}$ the inverse of the wave frequency for the time and $a\omega$ where $a$ is the amplitude for the velocity, equation (5) becomes

$$\rho_1 a\omega^2 + \rho_1 \frac{a\omega^2}{\lambda} = -\frac{\rho_1}{\lambda} + \mu_1 \frac{a\omega}{\lambda^2} + \rho_1 g$$

(6)

Neglecting the second term of the right hand side before the first term of the left hand side of equation (6) gives:

$$\mu_1 \frac{a\omega}{\lambda^2} \ll \rho_1 a\omega^2$$

or

$$\frac{\rho_1 a^2 \omega}{\mu_1} \gg 1$$

If the effect of viscosity is neglected $\mu = 0$, then the above condition is satisfied. Considering the second term of the left hand side of equation (6) small compared to the first gives

$$a\omega^2 \gg \frac{a^2 \omega}{\lambda}$$
This states that the amplitude of the wave must be small compared to the wavelength.

The two differential equations (1) and (2) can be solved once the appropriate boundary conditions are specified:

- The two fluids are considered unbounded in the $x$ (positive and negative) and $z$ (positive and negative) directions and their velocities are finite there.

- At $y = -\delta_1$, the $y$-component of the velocity of the lower fluid is zero

$$v_{1y} = -\frac{3f_1}{\delta y} \bigg|_{y = -\delta_1} = 0$$

(7)

- At $y = +\delta_2$, the $y$-component of the velocity of the upper fluid is zero

$$v_{2y} = -\frac{3f_2}{\delta y} \bigg|_{y = +\delta_2} = 0$$

(8)

- The conditions at the interface can be found by the following arguments. By definition, the mass of one phase leaving that phase across an interfacial area element is given by Kocamustafaogullari [11]
\[ \hat{\mathbf{m}}_1 = \rho_1 (\hat{\mathbf{v}}_1 - \hat{\mathbf{v}}_1) \cdot \hat{n}_1 \]

and

\[ \hat{\mathbf{m}}_2 = \rho_2 (\hat{\mathbf{v}}_2 - \hat{\mathbf{v}}_1) \cdot \hat{n}_2 \]

where \( \hat{\mathbf{v}}_1 \) denotes the interface velocity and \( \hat{n}_1 \) and \( \hat{n}_2 \) are the unit normal vectors pointing outwards. If a surface \( f \) is given by the equation

\[ f(x, y, t) = 0 \]

geometric considerations show that

\[ \hat{n}_1 = \frac{\mathbf{v}_f}{|\mathbf{v}_f|} \]

and

\[ \mathbf{v}_1 \cdot \hat{n}_1 = -\frac{\partial f}{|\nabla f|} \]
Therefore,

\[ \dot{\mathbf{m}}_1 = \frac{\rho_1}{|\mathbf{V}|} \left( \mathbf{v}_1 \cdot \mathbf{V} + \frac{\partial f}{\partial t} \right) \]

or in components

\[ \dot{\mathbf{m}}_1 = \frac{\rho_1}{|\mathbf{V}|} \left( v_{1x} \frac{\partial f}{\partial x} + v_{1y} \frac{\partial f}{\partial y} + v_{1z} \frac{\partial f}{\partial z} + \frac{\partial f}{\partial t} \right) \quad (9) \]

In this case

\[ f = y - \eta'(x, z, t) \]

where \( \eta' = \eta'(x, z, t) \) is the equation of the infinitesimal perturbation of the interface and can be written as

\[ \eta' = ae^{i(\omega t - k_x x - k_z z)} \quad (10) \]

\( k_x \) and \( k_z \) being the components of the wave number.

It is noted that

\[ \frac{\partial f}{\partial x} = -\frac{\partial \eta'}{\partial x} ; \quad \frac{\partial f}{\partial y} = 1 ; \quad \frac{\partial f}{\partial z} = -\frac{\partial \eta'}{\partial z} ; \quad \frac{\partial f}{\partial t} = -\frac{\partial \eta'}{\partial t} \]
Thus equation (9) becomes for fluid one

\[ \dot{m}_1 = \frac{\rho_1}{| \mathbf{v}_f |} \left[ -v_{lx} \frac{\partial n'}{\partial x} + v_{ly} - v_{lz} \frac{\partial n'}{\partial z} - \frac{\partial n'}{\partial t} \right] \]  

The same type of reasoning leads for the second fluid to

\[ \dot{m}_2 = \frac{\rho_2}{| \mathbf{v}_f |} \left[ -v_{2x} \frac{\partial n'}{\partial x} + v_{2y} - v_{2z} \frac{\partial n'}{\partial z} - \frac{\partial n'}{\partial t} \right] \]  

Thus, equations (7), (8), (11), and (12) in conjunction with the hypothesis of infinite velocities in the unbounded directions give the necessary boundary conditions to solve equations (1) and (2).

The method of small disturbances may now be applied (see for instance Chandrasekhar [12]). Expressing the velocities in constant and perturbed terms, one obtains

\[ v_{lx} = v_{lxo} + v'_{lx} \]  
\[ v_{ly} = v_{lyo} + v'_{ly} = v'_{ly} \]  
\[ v_{lz} = v_{lzo} + v'_{lz} \]
\( v_{2x} = v_{2x_0} + v_{2x}' \)  \hspace{1cm} (14)*

\( v_{2y} = v_{2y_0} + v_{2y}' = v_{2y} \)

\( v_{2z} = v_{2z_0} + v_{2z}' \)

and for the potentials

\[ \phi_1 = \phi_{10} + \phi_1' \]

\[ \phi_2 = \phi_{20} + \phi_2' \]

The Laplace's equations (1) and (2) for the disturbed parts only become

\[ \nabla^2 \phi_1' = 0 \]  \hspace{1cm} (15)

and

\[ \nabla^2 \phi_2' = 0 \]  \hspace{1cm} (16)

The corresponding boundary equations can be written as follows (if the

* It is assumed there is no steady component of velocities in the y-direction
second and higher orders in the unsteady parts are neglected): From equations (7) and (8)

\[ \text{at } y = -\delta_1 , \quad v_{1y} = \frac{\partial v_1}{\partial y} y = -\delta_1 = 0 \quad (17) \]

\[ \text{at } y = +\delta_2 , \quad v_{2y} = \frac{\partial v_2}{\partial y} y = +\delta_2 = 0 \quad (18) \]

The equations (11) and (12) at the interface \( y = \eta^* \) become

\[ \dot{m}_1 = \frac{\rho_1}{|v_f|} \left[ -v_{1x0} \frac{\partial \eta^*}{\partial x} + v_{1y} - v_{1zo} \frac{\partial \eta^*}{\partial z} - \frac{\partial \eta^*}{\partial t} \right] \]

\[ \dot{m}_2 = \frac{\rho_2}{|v_f|} \left[ -v_{2x0} \frac{\partial \eta^*}{\partial x} + v_{2y} - v_{2zo} \frac{\partial \eta^*}{\partial z} - \frac{\partial \eta^*}{\partial t} \right] \]

It is assumed that during the time of interest, the average film thickness does not change; otherwise, the lower fluid would grow infinitely or vanish completely. Therefore, the mass transfer terms must be set equal to zero and herewith one obtains at \( y = \eta^* \)

\[ -v_{1x0} \frac{\partial \eta^*}{\partial x} + v_{1y} - v_{1zo} \frac{\partial \eta^*}{\partial z} - \frac{\partial \eta^*}{\partial t} = 0 \]
Since by use of equations (3) and (4),

\[-v_{2x} \frac{\partial \eta}{\partial x} + v_{2y} - v_{2x} \frac{\partial \eta}{\partial z} - \frac{\partial \eta}{\partial t} = 0\]

the conditions at \( y = \eta \) become

\[-\frac{\partial \phi_1}{\partial y} = v_{1x} \frac{\partial \eta}{\partial x} + v_{1z} \frac{\partial \eta}{\partial z} + \frac{\partial \eta}{\partial t} \quad \text{(19)}\]

\[-\frac{\partial \phi_2}{\partial y} = v_{2x} \frac{\partial \eta}{\partial x} + v_{2z} \frac{\partial \eta}{\partial z} + \frac{\partial \eta}{\partial t} \quad \text{(20)}\]

Since \( \eta \) is not a function of \( y \), one can write

\[\frac{\partial \eta}{\partial t} \bigg|_{y = \eta} = \frac{\partial \eta}{\partial t} \bigg|_{y = 0}\]
\[ \frac{\partial n'}{\partial x} y = n' \quad y = 0 \]

\[ \frac{\partial n'}{\partial z} y = n' \quad y = 0 \]

and also subject to the same approximation as before,

\[ \frac{\partial \phi_1}{\partial y} y = \eta' \quad y = 0 \]

\[ \frac{\partial \phi_2}{\partial y} y = \eta' \quad y = 0 \]

The equations (19) and (20) are therefore valid at \( y = 0 \). Using the boundary conditions described above one can solve the differential equations (15) and (16) (for instance by using the method of separation of variables) and one gets:
\[ \phi_1 = M_1 e^{i(\omega t - k_x x - k_z z)} \frac{e^{k(y+\delta_1)} - e^{-k(y+\delta_1)}}{k e^{k\delta_1} - e^{-k\delta_1}} \]

and

\[ \phi_2 = M_2 e^{i(\omega t - k_x x - k_z z)} \frac{e^{k(y-\delta_2)} - e^{-k(y-\delta_2)}}{k e^{k\delta_2} - e^{-k\delta_2}} \]

Where

\[ M_1 = -a \left[ i\omega - v_{1x} i k_x - v_{1z} i k_z \right] \]

\[ M_2 = +a \left[ i\omega - v_{2x} i k_x - v_{2z} i k_z \right] \]

and

\[ k = \left[ k_x^2 + k_z^2 \right]^{1/2} \]

Note that this result reduces to Lamb's expression [9]

\[ \phi_1 = e^{i\omega t} \cosh x \frac{\cosh k(y+\delta_1)}{k \sinh (k\delta_1)} (-a i \omega) \]
if it is assumed that a two-dimensional case exists (no $z$), that no velocities ($v_{1x0} = 0, v_{1zo} = 0$) exist and that only the cosine part of the exponential $e^{ikx}$ is considered. The justification of not considering the "$-i \sin kx$" part is that it will give, for $\omega$ imaginary, an imaginary expression for $\phi'$ and therefore for the velocities.

The equations (21) and (22) allow the complete determination of the velocity field.

2.3 Wave Velocity

The momentum equations for the two incompressible fluids in irrotational motion are given by Milne-Thomson [13].

\[
\frac{p_1}{\rho_1} + \frac{1}{2} v_1^2 + gy - \frac{\partial \phi_1}{\partial t} = 0 \quad (24)
\]

\[
\frac{p_2}{\rho_2} + \frac{1}{2} v_2^2 + gy - \frac{\partial \phi_2}{\partial t} = 0 \quad (25)
\]

Using equations (13) and (14), and the linearized approximation

\[
\frac{1}{2} v_1^2 = \frac{1}{2}(v_{10} + v_1')^2 = \frac{1}{2} v_{1x0}^2 + v_{1x0} v_{1x} + \frac{1}{2} v_{1zo}^2 + v_{1zo} v_{1z}
\]

\[
\frac{1}{2} v_1^2 = \frac{1}{2}(v_{1x0}^2 + v_{1zo}^2) - v_{1x0} \frac{\partial \phi_1}{\partial x} - v_{1zo} \frac{\partial \phi_1}{\partial z} .
\]
Similarly,

\[
\frac{1}{2} \bar{v}_2^2 = \frac{1}{2}(v_{2x_0}^2 + v_{2z_0}^2) - v_{2x_0} \frac{\partial \phi_2}{\partial x} - v_{2z_0} \frac{\partial \phi_2}{\partial z}
\]

Consequently, the unsteady parts of equations (24) and (25) are written at \( y = \eta \)

\[
\frac{\dot{p}_1}{\rho_1} = \frac{\partial \phi_1}{\partial t} + v_{1x_0} \frac{\partial \phi_1}{\partial x} + v_{1z_0} \frac{\partial \phi_1}{\partial z} - g \eta
\]  

(26)

\[
\frac{\dot{p}_2}{2} = \frac{\partial \phi_2}{\partial t} + v_{2x_0} \frac{\partial \phi_2}{\partial x} + v_{2z_0} \frac{\partial \phi_2}{\partial z} - g \eta
\]  

(27)

The interfacial jump condition has been expressed by Kocamustafaogullari [11]

\[
\dot{p}_1 - \dot{p}_2 + \dot{m}_1 (\vec{v}_1 - \vec{v}_2) \cdot \hat{n}_1 = \sigma \left( \frac{1}{R_a} + \frac{1}{R_b} \right)
\]  

(28)

where \( \sigma \) is the surface tension coefficient and \( R_a \) and \( R_b \) the radii of curvature.

It is already known that

\[
\dot{m}_1 = \rho_1 \vec{v}_1 \cdot \hat{n}_1 - \rho_1 \vec{v}_1 \cdot \hat{n}_1
\]
and

\[ \mathbf{m}_2 = \rho_2 \mathbf{v}_2 \cdot \mathbf{n}_2 - \rho_2 \mathbf{v}_1 \cdot \mathbf{n}_2 \]

Since the mass of phase one which leaves phase one across an interfacial area element is equal to the mass of phase two which enters phase two across the same area:

\[ \dot{m}_1 + \dot{m}_2 = 0 \]

\[ -\dot{m}_1 (\rho_1 - \rho_2) = \rho_2 \rho_1 (\mathbf{v}_1 - \mathbf{v}_2) \cdot \hat{n}_1 \]

or

\[ (\mathbf{v}_1 - \mathbf{v}_2) \cdot \hat{n}_1 = -\dot{m}_1 \frac{\Delta \rho}{\rho_1 \rho_2} \]

where

\[ \Delta \rho = \rho_1 - \rho_2 \]

The interfacial condition (28) is then written as:
\[ P_1 - P_2 = \frac{m_1^2 \Delta \rho}{\rho_1 \rho_2} + \sigma \left( \frac{1}{R_a} + \frac{1}{R_b} \right) \]  

(29)

The radii of curvature can in their turn be transformed to give approximately:

\[
\frac{1}{R_a} = \frac{\partial^2 \eta^*}{\partial z^2} \left[ 1 + \left( \frac{\partial \eta^*}{\partial z} \right)^2 \right]^{3/2} = -\frac{\partial^2 \eta^*}{\partial z^2}
\]

and

\[
\frac{1}{R_b} = \frac{\partial^2 \eta^*}{\partial z^2} \left[ 1 + \left( \frac{\partial \eta^*}{\partial z} \right)^2 \right]^{3/2} = -\frac{\partial^2 \eta^*}{\partial z^2}
\]

Considering again disturbed and undisturbed parts, with

\[ \dot{m}_1^2 = (\dot{m}_{10} + \dot{m}_1^*)^2 \]

the equation (29) gives at \( y = \eta^* \)
This relation expresses the difference of pressure at the interface and takes into account the surface tension and the mass transfer effects.

How can the mass transfer terms be evaluated? The final purpose is to use this wave analysis for film boiling from a flat plate. In that case of boiling, the lower fluid (Index 1) becomes a vapor phase and the upper fluid (Index 2) a liquid phase. Assuming that the two phases are in thermodynamic equilibrium, from an energy balance we have according to Zuber and Dougherty [15]

\[ \dot{m}_1 \Delta i = q_{\text{tot}} \]  

(31)

where \( \Delta i \) is the latent heat of vaporization and \( q_{\text{tot}} \) the total heat flux from the plate. On the other hand, one can write

\[ q_{\text{total}} = (h_c + h_r)\Delta T \]  

(32)

where \( h_c \) is the heat transfer coefficient when there is no radiation, \( h_r \) the coefficient of heat transfer by radiation through the lower fluid and \( \Delta T \) is the temperature difference between the plate and the upper fluid which is assumed at saturation temperature.
Equating (31) and (32) gives

\[ T_2 = T_{\text{saturation}} \]

or separating as usual

\[ \dot{m}_1 = \frac{(h_c + h_r) \Delta T}{\Delta t} \]

\[ \dot{m}_{10} + \dot{m}_1 = \left( \frac{h_{co} + h_{ro}}{\Delta t} \right) \Delta T + \frac{h' c \Delta T}{\Delta t} \]

It is noted that there is no radiative disturbed term since the temperature is not perturbed. One can thus write

\[ \dot{m}_{10} \dot{m}_1 = h_{co} \left( 1 + \frac{h_{ro}}{h_{co}} \right) \frac{\Delta T}{\Delta t} + \frac{h' c \Delta T}{\Delta t} \]

or

\[ \dot{m}_{10} \dot{m}_1 = \left( \frac{h_{co} \Delta T}{\Delta t} \right)^2 \left( 1 + \frac{h_{ro}}{h_{co}} \right) \frac{h' c}{h_{co}} \]

(33)
By the definition of the conductive heat transfer coefficient, one obtains

\[ h_c = \frac{K_1}{\delta_1 + \eta^*} = \frac{K_1}{\delta_1 (1 + \frac{n^*}{\delta_1})} \approx \frac{K_1}{\delta_1} (1 - \frac{n^*}{\delta_1}) \]

where again the second and higher orders in \(n^*\) are neglected and where \(K_1\) is the thermal conductivity of phase one.

Since

\[ h_c = h_{co} + h_c^* \]

one finds

\[ \frac{h_c^*}{h_{co}} = -\frac{n^*}{\delta_1} \]

Introducing this result in equation (33), a final expression for the mass transfer terms is obtained:

\[ \dot{m}_{10} \dot{m}_1 = -\left[ \frac{h_{co} \Delta T}{\Delta I} \right]^2 \left[ 1 + \frac{h_{ro}}{h_{co}} \right] \frac{n^*}{\delta_1} \quad (34) \]
Substituting this into equation (30) leads to the relation of the pressure condition at the interface:

$$p_1 - p_2 = -2 \left( \frac{h_0 \Delta T}{\delta_1} \right)^2 \left[ 1 + \frac{h_{ro}}{h_{co}} \right] \rho_1 \rho_2 \frac{\Delta \rho}{\rho_1 \rho_2} \frac{\eta}{\delta_1} - \delta_1 \left( \frac{\partial^2 \eta}{\partial x^2} + \frac{\partial^2 \eta}{\partial z^2} \right)$$

(35)

The equations (26), (27), and (35), where the potentials $\phi_1$ and $\phi_2$ are given by equations (21) and (22) and $\eta$ by equation (10) can now be combined to obtain after rearrangement

$$\rho_1 \ \text{ctnh} \ (k \delta_1) (\omega - v_{1z0} k - v_{1z0} k_2) + \rho_2 \ \text{ctnh} \ (k \delta_2) (\omega - v_{2z0} k - v_{2z0} k_2)^2 =$$

$$k_2 \Delta \rho - 2k \left( \frac{h_0 \Delta T}{\delta_1} \right)^2 \rho_1 \rho_2 \frac{\Delta \rho}{\rho_1 \rho_2} \left( 1 + \frac{h_{ro}}{h_{co}} \right) \frac{1}{\delta_1} + \sigma k^3$$

Note that this expression reduces to Lamb's solution [9] in the simplified two-dimensional case with unlimited depths and no surface tension nor mass transfer effects.

The solution of this equation for $\omega$ gives the frequency equation of the interface which plays, as it will be seen, an important role in the stability analysis.
\[
\omega = \frac{\rho_1 V + \rho_2 W \pm \left[ -\rho_1 \rho_2 (V-W)^2 - X(\bar{\rho}_1 + \bar{\rho}_2) \right]^{1/2}}{\bar{\rho}_1 + \bar{\rho}_2}
\]  \quad (36)

where

\[
\bar{\rho}_1 = \rho_1 \text{ctnh} \; (k\delta_1)
\]

\[
\bar{\rho}_2 = \rho_2 \text{ctnh} \; (k\delta_1)
\]

\[
V = v_{1x_0} k_x + v_{1z_0} k_z
\]

\[
W = v_{2x_0} k_x + v_{2z_0} k_z
\]

\[
X = 2 \left( \frac{h\sigma}{\Delta_i} \right) \frac{\Delta p k}{\rho_1 \rho_2 \delta_1} (1 + \frac{h\sigma}{h_{co}}) - kg\Delta p - \sigma k^3
\]

This expression can be written in terms of the wave velocity \( c \) defined by

\[
c = \frac{\omega}{k}
\]

to obtain the dispersion equation
\[ c = \frac{\rho_1 \left( \frac{k}{k} v_{1x} + \frac{k}{k} v_{1z} \right) + \rho_2 \left( \frac{k}{k} v_{2x} + \frac{k}{k} v_{2z} \right)}{\rho_1 + \rho_2} \]  

\[ + \left\{ \frac{g \Delta \rho}{k (\bar{\rho}_1 + \bar{\rho}_2)} + \frac{\sigma k}{\bar{\rho}_1 + \bar{\rho}_2} - \frac{2 (h \cos \theta \Delta T)^2}{(\Delta \rho)^2 \rho_1 \rho_2 (\bar{\rho}_1 + \bar{\rho}_2) k \delta_1} (1 + \frac{h_{ro}}{n_{co}}) \right\} \]

\[ - \frac{\rho_1 \rho_2}{(\bar{\rho}_1 \bar{\rho}_2)^2} \left\{ \frac{k}{k} (v_{1x} - v_{2x}) + \frac{k}{k} (v_{1z} - v_{2z}) \right\}^2 \right\}^{1/2} \]

It is important to emphasize here that this expression is more general than many other previous results in the fact that it shows the influence on the wave velocity of the limited depths, mean fluid velocities, surface tension and mass transfer effects in a three-dimensional case.

As it was proposed and done by Zuber [3] such wave analysis relations can be used to predict the maximum heat flux as well as the minimum heat flux in pool boiling. In the following parts of this study we shall limit ourselves to the consideration of the minimum heat flux and the pool film boiling region.
CHAPTER III

STABILITY ANALYSIS APPLIED TO FILM BOILING

3.1 Rayleigh-Taylor Instability

In this chapter the Rayleigh-Taylor instability analysis will be applied to pool film boiling, and expressions for the critical wavelength which corresponds to the limit between stable and unstable conditions and for the most dangerous wavelength or the most noticeable wavelength in the unstable region will be derived. These values affect directly the bubbles spacing and size in film boiling.

From various visual observations drawn from Westwater [15], Berenson [4], Nishikawa [16] one can describe the following stages in pool film boiling from a horizontal surface:

Let us start with an approximately flat surface between the vapor and liquid phases (See Figure 2a). Under the action of some perturbation, disturbances of the interface appear; the vapor generated in their vicinity flows toward them and contributes to their growth (see Figure 2b). The protuberances are located in some regular lattice and the distance between them seems more or less constant. They depart from the interface as bubbles and the film becomes flat again (Figure 2c). At locations shifted from a constant quantity new disturbances in the interface are formed (Figure 2d) and depart so that the vapor film is flat again (Figure 2e).

In the Rayleigh-Taylor instability analysis, one assumes that the
Figure 2. Stages in Film Boiling.
velocities of the two phases are negligible. That means that the mean velocities are equal to zero:

\[ v_{1xo} = v_{1zo} = 0 \]

\[ v_{2xo} = v_{2zo} = 0 \]

Is this a reasonable assumption when it is applied to pool film boiling from a horizontal surface?

One seen immediately that since there is no forced convection the velocity of the upper fluid (Index 2) is zero, but it is not evident for the lower fluid. In their discussion of this hypothesis Berenson [4] and Hosler [17] conclude that it is valid near the minimum heat flux but it becomes less accurate when the \( \Delta T \) is increased. It must be noted that their wave analysis does not take into account the mass transfer terms. The same assumption will be used. The close agreement between the present theory and the experiments shows that even at high \( \Delta T \) the assumption is reasonable. The general expression of the phase velocity given by equation (37) becomes:

\[
C = \frac{\omega}{k} = \pm \left[ \frac{g}{k \rho_{12}} \frac{\Delta \rho}{\rho_{12}} + \frac{\sigma_k}{\rho_{12} \rho_{2}} - \frac{2(\Delta h_{co})^2}{(\Delta l)^2 \rho_1 \rho_2 (\rho_1 \rho_2) k_1} \left( 1 + \frac{h_{co}}{h_{co}} \right) \right]^{1/2}
\]

or
It is recalled that the perturbation \( \eta' \) was given by equation (10)

\[
i(\omega t - k_x x - k_z z)\]

\[
\eta' = a e
\]

one sees that the sign of \( \omega^2 \) will determine whether the perturbation will grow or decrease exponentially with time. Thus if \( \omega^2 \) is negative the interface will be unstable and if \( \omega^2 \) is positive it will be stable. The condition \( \omega^2 = 0 \) gives the limit between stability and instability and the corresponding wavenumber is called critical. This limiting case will be discussed first.

### 3.2 Critical Wavelength

Setting \( \omega^2 \) given by equation (38) equal to zero and remembering that

\[
k^2 = k_x^2 + k_z^2 \tag{23}
\]

one obtains

\[
\frac{2}{k_x} + \frac{2}{k_z} = -\frac{\Delta \rho}{\sigma} + \frac{2(h_{co} \Delta T)^2}{(\Delta t)^2 \rho_1 \rho_2 \rho_2 \rho_1 \rho_2 \rho_2 \rho_2 \rho_2} \frac{\Delta \rho}{h_{co}^2} (1 + \frac{h_{ro}}{h_{co}}) \tag{39}
\]
which is a first condition in order to determine the components of the critical wavenumber \( k_{xc} \) and \( k_{zc} \). A second condition can be found in the following argument.

Let us consider such a disturbed interface as described above at some fixed time when the bubbles are growing. (See Figure 3 which is a top view). One notices that some pattern is repeated all over the figure.

It has a losenge shape, limited by nodal lines and contains two elevated zones and two depressed. The distance between two crests is \( \lambda_x \) while the distance between the centers of the two depression zones is \( \lambda_z \). In Figure 3, these distances are not equal and have been chosen arbitrarily. The relation between \( \lambda_x \) and \( \lambda_z \) will now be determined. The surface \( S \) of the repeated area is given by

\[
S = \frac{2\lambda_x \lambda_z}{2} = 2 \lambda_x \lambda_z
\]

By the relation between the wavelength and the wavenumber one obtains

\[
S = \frac{2\pi}{k_x k_z} \quad (39a)
\]

The real system adopts the configuration of minimal energy. Since the energy of the wave is directly proportional to its area the system will minimize its area. Therefore, let us minimize the area \( S \) given by equation (39a) with the condition expressed by equation (23).
Figure 3. Schematic Boiling Pattern.
Following the Lagrangian multipliers method, the function $\psi$ is defined by

$$\psi = \frac{8\pi^2}{k_x k_z} + \nu(k_x^2 + k_z^2 - k^2)$$

one then calculates

$$\frac{3\psi}{3k_x} = -\frac{8\pi^2}{k_x k_z} + 2\nu k_x = 0$$

$$\frac{3\psi}{3k_z} = -\frac{8\pi^2}{k_z k_x} + 2\nu k_z = 0$$

$$\frac{3\psi}{3\nu} = k_x^2 + k_z^2 - k^2 = 0$$

and obtains

$$\nu = \frac{4\pi^2}{k_x^3 k_z} = \frac{4\pi^2}{k_z^3 k_x}$$

or
The real pattern is then given by Figure 4 where \( \lambda_x = \lambda_z \) and the repeating area is a square. This rejoins Berenson's [24] experimental results: "Visual observations of the bubble pattern which exists on a horizontal surface gave the impression that the bubbles are located in some type of regular lattice, perhaps hexagonal or square."

Combining the condition (39) and (40) gives

\[
\begin{align*}
\frac{k_x^2}{k_z^2} = k_x^2 = k_z^2 = & \frac{\Delta \rho}{2 \sigma} + \frac{(\Delta \rho)^2}{(\Delta \sigma)^2 \rho_1 \rho_2 \sigma_1 \sigma_2} (1 + \frac{h_{ro}}{h_{co}}) \\
\text{or in terms of wavelength and since } & \Delta \rho = \rho_1 - \rho_2
\end{align*}
\]

\[
\lambda_{xc} = \lambda_{zc} = \frac{2\pi}{\sqrt{\frac{g(\rho_2 \rho_1)}{2 \sigma} - \frac{(h_{co} \Delta T)^2}{(\Delta \sigma)^2 \rho_1 \rho_2 \sigma_1 \sigma_2} (1 + \frac{h_{ro}}{h_{co}})^{1/2}}}
\]

The gravity appears in the denominator of this formula; it has therefore a destabilizing effect which was expected since the lighter phase is below the heavier phase. On the contrary, the surface tension and the mass transfer terms contribute to the stability. One thus arrives at the same conclusions as previous investigators [5,6],[7,11]. Equation (41) can be rewritten as:
Figure 4. Schematic Boiling Pattern - Repeated Square.
\[
\lambda_{xc} = \lambda_{zc} = \frac{2\pi}{\left[ g\left(\rho_2 - \rho_1\right) - \frac{2}{2\sigma} \right]^{1/2} \left[ 1 - \frac{2\left(hco\Delta T\right)^2}{(\Delta i)^2 \rho_1 \rho_2 \delta_1 g \left(1 + \frac{h_{ro}}{h_{co}}\right)} \right]^{1/2}}
\] (42)

Let us define the vapor thrust number, \( M_q \),

\[
M_q = \frac{2\left(hco\Delta T\right)^2}{(\Delta i)^2 \rho_1 \rho_2 \delta_1 g \left(1 + \frac{h_{ro}}{h_{co}}\right)}
\]

A non-dimensional group, it is the ratio of the effects of mass transfer and gravity. It may be considered as a kind of Froude number where the inertia forces are replaced by the mass transfer term.

The equation (42) becomes then

\[
\lambda_{xc} = \lambda_{zc} = \frac{2\pi}{\left[ g\left(\rho_2 - \rho_1\right) - \frac{2}{2\sigma} \right]^{1/2} \left[ 1 - M_q \right]^{1/2}}
\] (43)

or in a non-dimensional form

\[
\frac{\lambda_{xc}}{\left[ \frac{\sigma}{g\left(\rho_2 - \rho_1\right)} \right]^{1/2}} = \frac{\lambda_{zc}}{\left[ \frac{\sigma}{g\left(\rho_2 - \rho_1\right)} \right]^{1/2}} = \frac{2\sqrt{2}}{\pi}
\] (44)

which is the final expression of the critical wavelength. Compare it with Lamb’s capillary waves analysis result [9]
\[ \lambda = 2\pi \left[ \frac{g}{8\left(p-P_1\right)} \right]^{1/2} \]  

It is emphasized again that our result is different from the usual purely hydrodynamical Rayleigh-Taylor instability analysis by the presence of the \( M_q \) term which accounts for heat transfer effects.

### 3.3 Prediction of the Change of Boiling Pattern

If the conditions are reached for which the vapor thrust number, \( M_q \), equals unity the critical wavelength becomes infinite. The boiling pattern should then be entirely different. That is exactly what is observed in experiments.

Grigull and Abadzic [1] and also Abadzic and Goldstein [2] have observed film boiling on a wire for conditions close to critical. At low heat flux their photographs show the usual pattern of bubbles leaving regularly the interface. As the heat flux is increased vapor columns are formed, then at some locations vapor sheets rise from the vapor film; and as the heat flux is increased further a vapor sheet covers the entire surface.

The following table summarizes the calculation of \( M_q \) for the characteristic example, photographed by Abadzic and Goldstein, of boiling \( \text{CO}_2 \) (at a pression of 71.4 bar and a saturation temperature of 29.5°C).
The observed change of flow pattern at high pressure is thus predicted by the above expressions when the $M_q$ term takes the value of unity. Physically, it means that the effect of the heat flux balances the gravity effect, that is, the vapor thrust is so important that it overcomes the effect of the gravity which tends to bring down the heavy liquid. As $M_q$ increases beyond unity the vapor production is so intense that it becomes a vapor sheet.

At low pressures however, the non-dimensional mass transfer term is generally small. But is increases when one leaves the minimum heat flux and goes further in the film boiling region, i.e., where $q$ and $\Delta T$ are increased. The value $M_q = 1$ for Nitrogen at atmospheric pressure is obtained when the heat flux peaks at $1.65 \times 10^3$ BTU/hr ft$^2$ and the temperature difference $\Delta T$ at $2.55 \times 10^3$ °F. At such high conditions the experimental information for boiling from a flat surface is not yet available.

At conditions where the $M_q$ term is larger than one, the present model for film boiling is, of course, no more valid and other theoretical analyses are to be used.

In this section one of the goals of this study has been achieved
that is, a criterion has been derived which predicts the change observed in the flow pattern for vapor bubbles to vapor sheets of film boiling at high pressure.

3.4 Most Dangerous Wavelength

If a disturbance has a wavelength larger than the critical wavelength it will grow exponentially with time. Among all these wavelengths leading to the unstability one has the most rapid growth and is therefore called the most dangerous.

From the first section of this chapter it is known that in the unstable region $\omega^2$ is negative. The growth rate of the disturbance $\partial \eta'/\partial t$ is

$$\frac{\partial \eta'}{\partial t} = i \omega a e$$

The fastest growth rate will thus be obtained by maximizing $(-\omega^2)$. In order to do that, let us calculate:

$$\frac{\partial}{\partial k} (-\omega^2) = 0$$

or with equation (38)

$$\frac{\partial}{\partial k} \left[ \frac{2(h_{co} \Delta T)^2}{(k_{co} \Delta T)^2} \frac{\Delta \rho k}{\rho_1 \rho_2 (\rho_1 p_2)^{\delta_1}} (1 + \frac{h_{ro}}{h_{co}}) - \frac{g \Delta \rho k}{\rho_1 p_2} - \frac{g k^3}{\rho_1 p_2} \right] = 0$$
where it is recalled that

\[ \rho_1 = \rho_1 \cosh(k\delta_1) \]

\[ \rho_1 = \rho_2 \cosh(k\delta_2) \]

one obtains

\[
\frac{2(h_c^T)\Delta}{(\delta \rho_1^2)\delta_1 \rho_1 \rho_2} \left( 1 + \frac{\hbar c}{\hbar} \right) - g\Delta k - \sigma k^3 \]

\[
\begin{bmatrix}
\rho_1 \delta_1 \cosh^2(k\delta_1) + \rho_2 \delta_2 \cosh^2(k\delta_2)
\end{bmatrix}
\]

\[
+ \frac{2(h_c^T)\Delta \rho}{(\delta \rho_1^2)\delta_1 \rho_1 \rho_2} - g\Delta \rho - 3\sigma k^2
\]

\[
\begin{bmatrix}
\rho_1 \coth(k\delta_1) + \rho_2 \coth(k\delta_2)
\end{bmatrix} = 0
\]
It will be noted that this expression reduces to the result previously found by Bankoff [18], if we omit the mass transfer term; (there is a misprint in equation (6) of this reference: \( k \) must multiply the first term of the numerator).

In film boiling the depth of the liquid phase is generally large and the vapor film is very thin. It is therefore assumed that

\[ k\delta_2 \gg 1 \]

and

\[ k\delta_1 \ll 1 \]

This is an improvement in regard to the frequent assumption of two infinitely deep fluids. Therefore,

\[ \bar{\rho}_2 = \rho_2 \text{ctnh}(k\delta_2) = \rho_2 \]

\[ \rho_2 \delta_2 \text{csch}^2(k\delta_2) = \rho_2 \delta_2 \frac{1}{k^2\delta_2^2} = \frac{\rho_2}{k^2\delta_2} = 0 \]

while for phase one

\[ (+): \) But the derivation of the most dangerous wavelength made in a subsequent paper by Kesselring and Alii [19] is incorrect.\]
\[ \bar{\rho}_1 = \rho_1 \csc \left( k\delta_1 \right) = \frac{1}{k\delta_1} \]

\[ \rho_1 \delta_1 \csc^2 \left( k\delta_1 \right) = \frac{\rho_1}{k^2\delta_1} \]

The condition (45) takes then a simplified form:

\[ \left[ \frac{2 \left( \frac{h}{c_0} \Delta T \right)^2 \Delta \rho}{(\Delta h)^2 \rho_1 \rho_2} (1 + \frac{h_{co}}{h_{co}} - g \Delta \rho k - \sigma k^3) \right] \left[ \frac{\rho_1}{k^2\delta_1} \right] + \]

\[ \left[ \frac{2 \left( \frac{h}{c_0} \Delta T \right)^2 \Delta \rho}{\delta_1 \rho_1 \rho_2} (1 + \frac{h_{co}}{h_{co}} - g \Delta \rho - 3\sigma k^2) \right] \left[ \frac{\rho_1}{k\delta_1} + \rho_2 \right] = 0 \]

Rearranged in terms of the non-dimensional group \( M_q \) this expression is a third order equation in \( k \).

\[ 2 M_q - 2 + \delta_1 \frac{\rho_2}{\rho_1} (M_q - 1)k + 4 \frac{\sigma}{g(\rho_2 - \rho_1)^2} k^2 + 3 \delta_1 \frac{\rho_2}{\rho_1} \frac{\sigma}{g(\rho_2 - \rho_1)^3} k^3 = 0 \]

Introducing a non-dimensional expression for \( k \)

\[ k^* = k\delta_1 \]

This third order equation takes a non-dimensional form
\[
2 M_q - 2 + \left(\frac{\rho_2}{\rho_1}\right)(M - 1) k^2 + 4 \frac{\sigma}{g(\rho_2 - \rho_1)^2 \delta_1^2} k^2 + 3 \frac{\rho_2}{\rho_1} \frac{\sigma}{g(\rho_2 - \rho_1)^2 \delta_1^2} k^3 = 0
\]

This expression gives the correct \( k \) allowing to find the most dangerous wavelength. Since it is not very easy to handle, a simplified equation which in many cases leads to a result approaching closely the exact result is proposed.

Notice that equation (45) can be written again as:

\[
-3 \sigma k^2 \left[ \frac{4}{3} \frac{\rho_1}{k \delta_1} + \frac{\rho_2}{k \delta_1} \right] - g \Delta \rho + \frac{2(h_{\text{co}} \Delta T)^2}{(\Delta i)^2 \rho_1 \rho_2 \delta_1} \frac{\Delta \rho}{(1 + \frac{h_{\text{co}}}{h_{\text{co}}})} = 0
\]

If the factor in brackets in the first term is nearly unity one can approximate this relation by

\[
3 \sigma k^2 = \frac{2(h_{\text{co}} \Delta T)^2}{(\Delta i)^2 \delta_1 \rho_1 \rho_2} \frac{\Delta \rho}{(1 + \frac{h_{\text{co}}}{h_{\text{co}}})} - g \Delta \rho
\]
or with non-dimensional groups

\[
k^+ = \frac{1}{3} \left[ \frac{g(\rho_2 - \rho_1)\delta_1}{\sigma} \right]^2 \left[ 1 - Mq \right]
\]  

The results of the exact and of the approximate equations are compared for four different fluids in film boiling conditions: water, freon 11, n-pentane, carbon tetrachloride. The following table summarizes the results.

<table>
<thead>
<tr>
<th>Type of Fluids</th>
<th>Heat Flux (q) Btu/hr ft(^2)</th>
<th>Temperature Difference (\Delta T) (^\circ\text{F})</th>
<th>(k^+) equation (47)</th>
<th>(k^+) equation (48)</th>
</tr>
</thead>
<tbody>
<tr>
<td>Water</td>
<td>(1.1 \times 10^1)</td>
<td>(2.85 \times 10^2)</td>
<td>(3.31 \times 10^{-2})</td>
<td>(3.27 \times 10^{-2})</td>
</tr>
<tr>
<td>Freon 11</td>
<td>(5.7 \times 10^3)</td>
<td>(1.6 \times 10^2)</td>
<td>(2.72 \times 10^{-2})</td>
<td>(2.45 \times 10^{-2})</td>
</tr>
<tr>
<td>N-Pentane</td>
<td>(7.7 \times 10^3)</td>
<td>(2.06 \times 10^2)</td>
<td>(4.33 \times 10^{-2})</td>
<td>(4.07 \times 10^{-2})</td>
</tr>
<tr>
<td>Carbon Tetrachloride</td>
<td>(6.75 \times 10^3)</td>
<td>(1.93 \times 10^2)</td>
<td>(3.09 \times 10^{-2})</td>
<td>(2.86 \times 10^{-2})</td>
</tr>
</tbody>
</table>

The difference between the values of the \(k^+\)'s is so small that one can reasonably use equation (48).

Remembering that equations (23) and (40) give
\[ k^2 = k_x^2 + k_z^2 = 2k_x^2 = 2k_z^2 \]  

(49)

the components of the most dangerous wavenumber are found

\[ k_{xm} = k_{zm} = \left( -\frac{g\Delta \rho}{6\sigma} + \frac{2(h_{co} \Delta T)^2}{6(\Delta t)^2 \sigma_1 \rho_2 \delta_1} \left(1 + \frac{h_{co}}{h_{co}}\right) \right)^{1/2} \]  

(50)

or in terms of wavelength

\[ \lambda_{xm} = \lambda_{zm} = \frac{2\pi}{\sqrt{g(\rho_2 \rho_1)} - \frac{2(h_{co} \Delta T)^2(\rho_2 \rho_1)}{(\Delta t)^2 \sigma_1 \rho_2 \delta_1} \left(1 + \frac{h_{co}}{h_{co}}\right)} \left(1 - M_q\right)^{1/2} \]  

(51)

which becomes with non-dimensional groups

\[ \lambda_{xm} = \lambda_{zm} = \frac{2\pi}{\sqrt{g(\rho_2 \rho_1)/6\sigma} \left(1 - M_q\right)} \]  

(51)

or
This relation gives thus the components of the most dangerous wavelength, i.e., the wavelength which corresponds to the maximum growth rate of the disturbance. The effect of our three-dimensional analysis is noted in the factor $2\sqrt{6}$. Indeed, a factor $2\sqrt{3}$ was obtained in the two-dimensional formulation. Another difference with this last approach is, of course, the presence of the $M_q$ term. By comparison of equations (44) and (52) it is interesting to note that

$$\lambda_{xm} = \lambda_{zm} = \sqrt{3} \lambda_{xc} = \sqrt{3} \lambda_{zc}$$

It has thus been shown in this chapter that the liquid vapor interface in film boiling is unstable when the wavelength is larger than the critical wavelength given by equation (44) and stable otherwise. In contrast to gravity, the surface tension and mass transfer have a stabilizing action. Equation (52) constitutes the expression of the wavelength which will be the most dangerous since it leads to the biggest and thus most noticeable growth rate.
3.5 Most Unstable Disturbance

The maximized expression of $(-\omega^2)$ can now be obtained by introducing in it the most dangerous wavenumber.

Equation (33) is combined with equations (49) and (50) to yield the following result

$$-\omega^2 = \frac{2}{3} \left[ \frac{g(\rho_2 - \rho_1)}{\rho_1 + \rho_2} - \frac{2(h_{co} \Delta T)^2 (\rho_2 - \rho_1)}{(\Delta t)^2 \rho_1 \rho_2 (-\rho_1 + \rho_2) \delta_1} (1 + \frac{h_{ro}}{h_{co}}) \right]$$

$$= \left[ \frac{g(\rho_2 \rho_1)}{3\sigma} - \frac{2(h_{co} \Delta T)^2}{3(\Delta t)^2 \sigma \rho_1 \rho_2 \delta_1} (1 + \frac{h_{ro}}{h_{co}}) \right]^{1/2}$$

The most unstable disturbance $\eta^*_{m}$ is thus obtained from this equation and equation (10)

$$\beta t = i k_{xm} x - i k_{zm} z$$

$$\eta^*_{m} = a e$$

where the growth coefficient $\beta$ is given by:
\[
\beta = \left[ \frac{2g(\rho_2 - \rho_1)}{3(\rho_1 + \rho_2)} - \frac{4(h_{co} \Delta T)^2 (\rho_2 - \rho_1)}{3(\Delta 1)^2 \rho_1 \rho_2 (\rho_1 + \rho_2) \delta_1} \left(1 + \frac{h_{ro}}{h_{co}}\right) \right]^{1/2}
\]

\[
= \left[ \frac{g(\rho_2 - \rho_1)}{3 \sigma} - \frac{2(h_{co} \Delta T)^2 (\rho_2 - \rho_1)}{3(\Delta 1)^2 \rho_1 \rho_2 \delta_1} \right]^{1/4}
\]

It is possible to rewrite this with the help of the usual dimensionless group:

\[
\beta = 2^{1/2} \frac{3}{3^{3/4}} \frac{1}{(\rho_1 + \rho_2)^{1/2}} \left[ \frac{g(\rho_2 - \rho_1)}{\sigma} \right]^{1/2} \left[ \frac{g(\rho_2 - \rho_1)}{\sigma} \right]^{1/4} \left[ 1 - \frac{M^4}{q} \right]^{3/4}
\]

In this relation \( \rho_1 \) and \( \rho_2 \) are still functions of the wavenumber and have also to be replaced by their appropriate values determined from the previous hypothesis concerning the depths of the two phases.

\( \bar{\rho}_2 = \rho_2 \)

and

\( \bar{\rho}_1 = \frac{\rho_1}{k \delta_1} \)
Introducing in this last expression the most dangerous wavenumber leads to

$$\beta = \frac{2^{1/2}}{3} \left[ \frac{g(\rho_2 - \rho_1)}{\rho_1} \right]^{1/2} \left[ \frac{g(\rho_2 - \rho_1)}{\sigma} \right]^{1/4} \left[ \frac{g(\rho_2 - \rho_1)}{\rho_1} \frac{2}{\sigma} \right]^{1/4} \left[ 1 - \frac{M}{q} \right]^{1/4}$$

This expression gives thus the growth coefficient (which has the dimension of the inverse of a time) for the most unstable disturbance. One observes the effects on this relation of the three-dimensional analysis by the coefficients, of the vapor depth by the factor $\frac{\delta_1}{\sqrt{3}}$ and of the mass transfer by the presence of $M_q$. Another evidence for the validity of the analysis is shown by equation (54). Note that when the vapor thrust number $M_q$ approaches unity the growth coefficient $\beta$ approaches zero. Therefore, since $\beta$ has the dimension of the inverse of a time, that is, of frequency, the period of oscillations tends to infinity. The phenomenon ceases to be periodic both in time and in space. The covering vapor sheet results in a stable boiling pattern.
CHAPTER IV

DIAMETER AND PERIOD OF BUBBLE RELEASE

4.1 Diameter of Bubble at Breakoff

The disturbances created on the interface grow in shape of approximately spherical bubbles whose diameters at breakoff and frequency of release will be the next subject of investigation.

In the Figure 4 which represents a projection of the liquid vapor interface on a horizontal surface, one may consider one of the repeated squares. As described before, two bubbles are formed and grow simultaneously in such an area. Westwater and Santangelo [15] observed that the bubble breaks at the nodal lines. Therefore, the shape of the bubble is idealized by a sphere whose diameter $D_b$ is given by the length of the side of the square on the nodal lines

$$D_b^2 = \left(\frac{x}{2}\right)^2 + \left(\frac{y}{2}\right)^2 = 2\left(\frac{x}{2}\right)^2 = 2\left(\frac{y}{2}\right)^2 = \frac{x^2}{2} + \frac{y^2}{2}$$

or

$$D_b = \frac{x}{\sqrt{2}} = \frac{y}{\sqrt{2}}$$  \hspace{1cm} (55)
where the wavelength components \( \lambda_x \) and \( \lambda_z \) in the spectrum

\[
\lambda_{xc} = \lambda_{zc} < \lambda_x = \lambda_z < \lambda_{xm} = \lambda_{zm} \tag{56}
\]

are taken following the method discussed by Zuber [3]. Combining equation (55) with equation (43) and (51) leads to

\[
\frac{2\pi}{\left[\frac{g(\rho_2 - \rho_1)}{\sigma}\right]^{1/2}} \left[\frac{1 - M_q}{1 - M_q} \right]^{1/2} \leq D_b \leq \frac{2\pi\sqrt{3}}{\left[\frac{g(\rho_2 - \rho_1)}{\sigma}\right]^{1/2}} \left[\frac{1 - M_q}{1 - M_q} \right]^{1/2}
\]

which can be rearranged in a non-dimensional form:

\[
\frac{2\pi}{\left[1 - M_q\right]^{1/2}} \leq D_b^+ \leq \frac{2\pi\sqrt{3}}{\left[1 - M_q\right]^{1/2}} \tag{57}
\]

where the dimensionless diameter of the bubble at breakoff is

\[
D_b^+ = \frac{D_b}{\left[\frac{\sigma}{g(\rho_2 - \rho_1)}\right]^{1/2}} \tag{58}
\]
It is interesting to compare this result with the expressions most often used in the literature.

In his original two-dimensional analysis Zuber [3] found

\[ \pi < D_b^+ < \sqrt{3} \pi \]

On the other hand, Berenson [4] determined from experiments of film boiling on a horizontal surface

\[ D_b^+ = 4.7 \]

From stability characteristics of the neck surface which connects the bubble to the interface Kiper [20] proposed a maximum bubble size given by

\[ D_b^+ = 9.28 \]

Lienhard and Wong [21] have shown that the heater geometry affects the diameter of the bubble at breakoff: the results being different if it is a flat plate, a large or a small wire. The present analysis concerns film boiling from a flat plate. Only a few experiments have been carried out and reported for that geometry.

Hosler and Westwater [8] data concerning mainly the minimum heat flux region are probably among the most important of these. They use water and freon 11 in their experiments; as they point it out these two
fluids have very different physical properties and constitute "a severe test for any theoretical or empirical expression for boiling."

The comparison between our expression of $D_b^+$ and their measurements at the minimum heat flux conditions is therefore presented in the following table

<table>
<thead>
<tr>
<th>Analysis</th>
<th>Experiments [8]</th>
</tr>
</thead>
<tbody>
<tr>
<td>$N_q$</td>
<td>$D_b^+$, min.</td>
</tr>
<tr>
<td>Water</td>
<td>$8 \times 10^{-4}$</td>
</tr>
<tr>
<td>Freon 11</td>
<td>$5.8 \times 10^{-3}$</td>
</tr>
</tbody>
</table>

In both cases we notice that the dimensionless term $N_q$ is very small and its effect on $D_b^+$ is nearly negligible. However, it is not always the case, as it is known from the previous chapter.

4.2 Period of Bubble Release

As in the beginning of this chapter, let us consider a single bubble generating area, and call $\tau$ the time which elapses between the formation of two bubbles on the same location (See Figure 2). The frequency of bubble release is the inverse of this time, i.e.,

$$f = \frac{1}{\tau}$$
From the figure it is seen that the time it takes for the boundary to grow one height equal to the bubble diameter is

$$t = \frac{T}{4}$$

But also by definition

$$t = \frac{D_b}{\Delta \eta/\partial t}$$

Consequently the frequency is given by

$$f = \frac{1}{4} \frac{\Delta \eta^*}{\partial t} \frac{1}{D_b} \quad (59)$$

The value of $D_b$ is already known; how can $\Delta \eta^*/\partial t$ be evaluated?

From equation (53)

$$\frac{\Delta \eta^*}{\partial t} = \beta \eta$$

From his experimental observations Lewis [22] noted that the amplitude of the wave increases exponentially until it reaches a maximum value approximately equal to 0.4 times the wavelength. It will be noted here that this value is considerably less restrictive than the assumption of the linearized theory.
Since \( \eta \) varies from an infinitesimal value to that upper limit a mean value for the growth rate can be used:

\[
\frac{3 \eta'}{\beta t} = \beta \frac{0.4 \lambda x}{2} = 0.2 \beta \lambda x
\]  

(60)

The equation (59) can then be transformed:

\[
f = 0.05 \beta \lambda x \frac{1}{D_b}
\]

Replacing \( D_b \) by its expression given by equation (55) yields to

\[
f = 0.05 \sqrt{2} \beta
\]

The value of the growth coefficient has been determined by equation (54). By substitution one finds:

\[
f = 0.033 \left[ \frac{g(\rho_2 - \rho_1)}{\rho_1} \right]^{1/2} \left[ \frac{g(\rho_2 - \rho_1)}{\sigma} \right]^{1/4} \left[ \frac{g(\rho_2 - \rho_1) \delta_1^2}{\sigma} \right]^{1/4} \left( 1 - M_q \right)
\]

\[
\left\{ 1 + \frac{1}{\sqrt{3}} \frac{\rho_2}{\rho_1} \left[ \frac{g(\rho_2 - \rho_1) \delta_1^2}{\sigma} \right]^{1/2} \left[ 1 - M_q \right] \right\}
\]
This frequency of bubble release can be rewritten in a non-dimensional form.

\[ f^+ = 0.033 \left[ \frac{g (\rho_2 - \rho_1) \delta_1}{\sigma} \right]^{1/4} \left[ \frac{1 - \frac{\rho_2}{\rho_1}} {1 + \frac{1}{\sqrt{3}} \frac{\rho_2}{\rho_1} \left[ \frac{g (\rho_2 - \rho_1) \delta_1}{\sigma} \right]^{1/2} \left[ 1 - \frac{\rho_2}{\rho_1} \right]^{1/2}} \right]^{1/2} \]

where the dimensionless frequency \( f^+ \) is defined by:

\[ f^+ = \frac{f}{\left[ \frac{g (\rho_2 - \rho_1)}{\rho_1} \right]^{1/2} \left[ \frac{g (\rho_2 - \rho_1)}{\sigma} \right]^{1/4}} \]

The comparison between this frequency of bubble release and the measurements of Hosler and Westwater is presented in the following table. The calculations have been performed for the inverse of the non-dimensional bubble frequency the dimensionless period \( \tau^+ \) and for the same fluids and conditions as in the previous section.

<table>
<thead>
<tr>
<th>Analysis</th>
<th>Experiments [8]</th>
</tr>
</thead>
<tbody>
<tr>
<td>( \tau^+ )</td>
<td>( \tau^+ ), ( \tau^+ ), ( \tau^+ ), ( \tau^+ )</td>
</tr>
<tr>
<td>Water</td>
<td>5.92 (10^2)</td>
</tr>
<tr>
<td>Freon 111</td>
<td>2.41 (10^2)</td>
</tr>
</tbody>
</table>
One sees immediately the good agreement between the theory and the experiments. Furthermore, from the previous estimation of the bubble diameter it is known that the $N_q$ term is small for such conditions near the minimum heat flux at atmospheric pressure; therefore, it does not affect considerably the expressions of the period calculated above. It should however become more important at high heat fluxes and pressures. Experimental verification of this on horizontal flat surfaces is badly needed.
CHAPTER V

HEAT TRANSFER IN FILM BOILING

5.1 Determination of the Minimum Heat Flux

This chapter is related to two specific heat transfer subjects: the prediction of the minimum heat flux and the determination of the heat transfer coefficient in pool film boiling. Two different approaches are used. The first one which follows Zuber's model is presented next while the second based on Berenson's film boiling analysis is discussed in the following section.

Let's assume that the flat horizontal surface on which the film boiling takes place has an area $ab$; first $n$, the number of bubbles released per unit time in that area, will be evaluated.

Consider in Figure 4 which represents the flow pattern one of the repeating squares of area $2\lambda_x^2$. It contains four bubble generating locations. (Indeed, as described before, in half a period two bubbles grow simultaneously in the square and after another half period two other bubbles have grown in shifted positions; which makes a total of four). The number of bubbles $n$ is thus the product of the number of squares in the area of interest $ab$ by four times the frequency of bubble release

\[ n = \frac{ab}{2\lambda_x^2} \cdot 4 \cdot f \]
The frequency to be used for the determination of the minimum heat flux is, following the method of Zuber [3], the frequency obtained by the interface stability analysis and given by equation (59). This substitution gives:

\[ n = \frac{ab}{2\lambda_x^2} \cdot 4 \cdot \frac{1}{4} \frac{\partial n'}{\partial t} \frac{1}{D_b} \]

which can in turn be combined with the value already obtained for \( D_b \) in equation (55) to yield

\[ n = \frac{ab}{\sqrt{2}} \frac{1}{\lambda_x^3} \frac{\partial n'}{\partial t} \]

Therefore, the number of bubbles released per unit time and unit area is

\[ n = \frac{1}{\sqrt{2}} \frac{1}{\lambda_x^3} \frac{\partial n'}{\partial t} \]  

(62)

On the other hand, the vapor flow rate per unit area carried away by the assumed spherical bubbles is

\[ \dot{m}_1 = \rho_1 \cdot \frac{4\pi}{3} \left( \frac{\lambda_x}{2\sqrt{2}} \right)^3 \cdot n \]

or after rearrangement with equation (62)
\[
\dot{m}_1 = \rho_1 \frac{\pi}{24} \frac{\partial n}{\partial t}
\]

The energy balance of equation (31) gives the expression of the minimum heat flux

\[
q_{\text{min}} = \dot{m}_1 \Delta t = \rho_1 \frac{\pi}{24} \frac{\partial n}{\partial t} \Delta t
\]

Substituting \(\partial n/\partial t\) by its value given by equation (60) where \(\beta\) and \(\lambda_x\) are replaced by their expressions as given in equations (56) and (51) leads to

\[
0.110 \left[ \frac{g(\rho_2 - \rho_1)}{\rho_1} \right]^{1/2} \left[ \frac{g(\rho_2 - \rho_1)\delta_1^2}{\sigma} \right]^{1/4} \left[ 1 - \frac{M_q}{1} \right]^{1/2} \left[ \frac{g(\rho_2 - \rho_1)\delta_1^2}{\sigma} \right]^{1/4} \left\{ 1 + \frac{1}{\sqrt{3}} \left[ \frac{g(\rho_2 - \rho_1)\delta_1^2}{\sigma} \right] \left[ 1 - \frac{M_q}{1} \right] \right\}^{1/2}
\]

\[
\leq q_{\text{min}}^<
\]

\[
0.190 \left[ \frac{g(\rho_2 - \rho_1)}{\rho_1} \right]^{1/2} \left[ \frac{g(\rho_2 - \rho_1)\delta_1^2}{\sigma} \right]^{1/4} \left[ 1 - \frac{M_q}{1} \right]^{1/2} \left[ \frac{g(\rho_2 - \rho_1)\delta_1^2}{\sigma} \right]^{1/4} \left\{ 1 + \frac{1}{\sqrt{3}} \left[ \frac{g(\rho_2 - \rho_1)\delta_1^2}{\sigma} \right] \left[ 1 - \frac{M_q}{1} \right] \right\}^{1/2}
\]
This two limiting expressions of the minimum heat flux in pool film boiling can be rewritten in a non-dimensional form

\[
\frac{0.110 \left[ 1 - M_q \right]^{1/2} \left[ 1 + \frac{\rho_2}{\rho_1} \right]^{1/2}}{\left\{ \frac{1}{\sqrt{3}} \frac{\rho_2}{\rho_1} \left[ 1 - M_q \right]^{1/2} + \left[ \frac{\sigma}{g(\rho_2 - \rho_1) \delta_1} \right]^{1/2} \right\}^{1/2}} \leq q_{\text{min}}^{+} \leq \frac{0.190 \left[ 1 - M_q \right]^{1/2} \left[ 1 + \frac{\rho_2}{\rho_1} \right]^{1/2}}{\left\{ \frac{1}{\sqrt{3}} \frac{\rho_2}{\rho_1} \left[ 1 - M_q \right]^{1/2} + \left[ \frac{\sigma}{g(\rho_2 - \rho_1) \delta_1} \right]^{1/2} \right\}^{1/2}}
\]

where \( q_{\text{min}}^{+} \) the dimensionless minimum heat flux is defined by

\[
q_{\text{min}}^{+} = \frac{q}{\rho_1 \Delta T \left[ \frac{g(\rho_2 - \rho_1)}{(\rho_1 + \rho_2)^2} \right]^{1/4}}
\]

a usual group in the literature.

These analytical expressions are once more compared with Hosler and Westwater [8] experiments of boiling from a flat aluminum heating surface 8 inches square; the following table is obtained where the agreement is satisfactory.
It is emphasized above that the influence of the $M_q$ term on the diameter at breakoff and on the frequency of bubble release is not very appreciable for low heat fluxes and temperature differences at atmospheric pressure. The same holds of course for the determination of the minimum heat flux itself.

<table>
<thead>
<tr>
<th></th>
<th>Analysis</th>
<th>Experiments [8]</th>
</tr>
</thead>
<tbody>
<tr>
<td>Water</td>
<td>$0.143 \leq q_{\text{min}}^+ \leq 0.247$</td>
<td>$q_{\text{min}}^+ \approx 0.206$</td>
</tr>
<tr>
<td>Freon 11</td>
<td>$0.135 \leq q_{\text{min}}^+ \leq 0.234$</td>
<td>$q_{\text{min}}^+ \approx 0.194$</td>
</tr>
</tbody>
</table>

Hosler and Westwater [8] explain this rather low value by the use of a too small heating horizontal surface: "Since the interbubble distance expected in film boiling with ordinary liquids is in the order of one inch, there may be a significant edge effect with a surface only two inch diameter."

Varying his assumptions concerning the bubble velocity at breakoff, the relation between diameter and wavelength or the flow pattern, Zuber
[3,23] has proposed different expressions of the minimum heat flux:

\[
q^+ = 0.130 \
(64a)
\]

\[
q^+ = 0.099 \
(64b)
\]

\[
q^+ = 0.176 \
(64c)
\]

\[
q^+ = 0.193 \
(64d)
\]

\[
q^+ = 0.013 \
(64e)
\]

Both the present analysis and the experimental results noted above show that equations (64c) and (64d) are to be recommended for film boiling from a flat surface. A fact known by many experimentators is also recognized: the results of Zuber's two-dimensional analysis although independent of thermal transport properties yield to acceptable values of the minimum heat flux at low pressures.

5.2 Heat Transfer Coefficient in Film Boiling

In this section Berenson's model [24] for the determination of the heat transfer coefficient in film boiling is modified by introducing in it the results of the previous wave stability analysis. This will give an expression of this coefficient valid not only in the vicinity of the minimum heat flux but also much higher in the film
boiling region.

The purpose is to evaluate the thickness $\delta_1$ of the vapor film from which the heat transfer coefficient is immediately deduced.

A part of the vapor produced at the interface compensates the decrease of the film thickness between the bubble domes. Therefore, there, the film thickness $\delta_1$ is approximately constant. Another part of the vapor produced flows towards these domes to contribute to their growth and finally their departure as bubbles.

A representation similar to Berenson's model is adopted (See Figure 5). The vapor velocity $V_1$ is assumed parallel to the flat heating surface and directed in the radial direction. The system exhibits a cylindrical symmetry. (See also Figure 6). The vapor flow rate flowing radially $G_1$ is given by

$$G_1 = \rho_1 V_1 \pi r^2 \delta_1$$  \hspace{1cm} (65)

In the following equations the heat transfer by radiation through the vapor film will not be considered. In other words, only one of the part of the total heat flux $q_{tot}$ of equation (32) is examined:

$$q_c = h_c \Delta T = q_{tot} - q_r$$  \hspace{1cm} (66)
Figure 5. Model of Film Boiling.
Figure 6. Single Bubble Generating Area.
The radiative contribution $q_r$ to the total heat flux from the surface can be in a first approach determined by [25],

$$q_r = \varepsilon \Sigma (T_w^4 - T_r^4)$$  \hspace{1cm} (67)

where $\varepsilon$ is the heated surface emissivity and $\Sigma$ the Stefan Boltzmann constant.

This elimination of the radiative heat transfer effect leads to introduce a dimensionless group other than the $M_q$ term which was defined by

$$M_q = \frac{2(h_c \Delta T)^2}{(\Delta i)^2 \rho_1 \rho_2 \delta_1 g} \left(1 + \frac{h_r}{h_c}\right)$$

Let this new non-dimensional group $N_q$ be given by:

$$N_q = \frac{2(h_c \Delta T)^2}{(\Delta i)^2 \rho_1 \rho_2 \delta_1 g} \hspace{1cm} (68)$$

which is exempt of radiative term and which will be used in the following derivation. Note for further use the relation:
\[
N_q = \frac{M_q}{(1 + \frac{h_r}{h_c})}
\]

(69)

The amount of heat passing through the vapor film is thus (Figure 5)

\[
\frac{K_1}{\delta_1} \Delta T (\pi r_A^2 - \pi r^2)
\]

which is equal to

\[
G_i \Delta i
\]

where \( \Delta i \) is the average enthalpy difference between vapor and liquid.

Equating these two expressions where \( G_1 \) has been replaced by its value from equation (65) gives the vapor velocity in the flat film

\[
V_1 = \frac{K_1 \Delta T (\pi r_A^2 - \pi r^2)}{\rho_1 (\Delta i) \delta_1^2}
\]

Considering the three-dimensional flow pattern (Figure 6) one sees that the vapor generated in an area equal to \( \lambda_x^2 \) flows into one bubble, therefore

\[
\pi r_A^2 = \lambda_x^2
\]
Replacing in the above expression of the velocity, one obtains

$$V_1 = \frac{K_1 \Delta T (\lambda_x^2 - \pi r^2)}{\rho_1 (\Delta t) \delta_1^2}$$

(70)

If the momentum forces are neglected before the viscous forces, the momentum equation can be written in the same way as Bromley [26] did

$$\frac{dP}{dr} = \frac{\xi \mu_1 V_1}{\delta_1^2}$$

where $\xi$ is a constant whose value will be determined later.

Introducing the value of the vapor velocity determined in equation (70) into this expression yields to

$$\frac{dP}{dr} = \frac{\xi \mu_1 K_1 \Delta T (\lambda_x^2 - \pi r^2)}{\rho_1 (\Delta t) \delta_1^4 \frac{2\pi r}{2\pi r}}$$

This relation can be integrated between position $A$ (at radius $r_A$ and pressure $P_A$) and position $B$ (at the radius $r_B$ and pressure $P_B$), making use of a value of $r_B$ equal to the one-half bubble diameter which is given by equation (55)

$$r_B = \frac{1}{2} D_b = \frac{\lambda_x}{2\sqrt{2}}$$
to obtain

$$P_A - P_B = 0.081 \frac{\xi \mu_1 K_1 T}{\rho_1 \delta_1^4 (\Delta i)} \lambda_x^2$$  \hspace{1cm} (71)$$

It is now assumed that the appropriate wavelength $\lambda_x$ can be obtained from the previous results of the stability analysis applied to film boiling and that it is legitimate to replace $\lambda_x$ by its maximum value $\lambda_{xm}$ the most dangerous wavelength. From equation (51)

$$\lambda_{xm} = \frac{24 \pi^2 \sigma}{g(\rho_1 - \rho_2) \left[1 - N_q \right]}$$  \hspace{1cm} (72)$$

Combining equations (71) and (72) gives

$$P_A - P_B = \frac{6.107 \xi \mu_1 K_1 \Delta T \sigma}{\rho_1 (\Delta i) \delta_1^4 g(\rho_2 - \rho_1) (1 - N_q)}$$

It is possible to evaluate this pressure difference by another means. Let $P_o$ be the pressure at a height $\gamma$ above the vapor film. The difference of pressure between $P_A$ and $P_o$ will be equal to

$\gamma \rho_2 g$ plus a term due to the difference of pressure at the interface. This same last term will be present in the difference of pressure between $P_B$ and $P_o$ which contains also $\gamma \rho_1 g + \frac{2 \sigma}{D_{b/2}}$. 
Therefore

\[ P_A - P_B = \gamma \rho_2 g - \gamma \rho_1 g - \frac{2\sigma}{D_b} \]  \quad \text{(74)}

Borishansky cited by Berenson [24] measured \( \gamma \) to be

\[ \gamma = 0.68 \ D_b \]  \quad \text{(75)}

If \( D_b \) is replaced as above by \((\lambda_{\text{ext}})/(\sqrt{2})\), combining equations (51), (74), and (75) one obtains

\[ P_A - P_B = \frac{g(\rho_2 - \rho_1)}{8.88 \left[ \frac{g(\rho_2 - \rho_1)}{\sigma} \right]^{1/2} \left[ 1 - N_q \right]} \left[ 65.76 - 3.26 (1 - N_q) \right] \]  \quad \text{(76)}

Equating equations (76) and (73) and solving for \( \delta_1 \) yields to

\[ \delta_1 = \left\{ \frac{54.3 \ \xi}{\left[ 65.76 - 3.26 (1 - N_q) \right] \left[ 1 - N_q \right]^{1/2} \rho_1 \Delta i \ g(\rho_2 - \rho_1) \sqrt{\rho_2 - \rho_1}} \right\}^{1/4} \]

The fact that only a part of the surface area is covered by a film of constant thickness must now be taken into account, and following Berenson's method the equation above is multiplied by the ratio of the total surface area to the area between the bubbles. Considering
Figure 6 this ratio is seen to be equal to two which yields to

\[
\delta_1 = \left\{ \frac{870 \xi}{65.76 - 3.26 (1 - N_q)[1 - N_q]} \right\}^{1/2} \frac{\mu_{1} K_{1} \Delta T}{\rho_{1} \Delta t \sqrt{g(\rho_2 - \rho_1)}} \right\}^{1/4}
\]

Since by definition

\[
q = h_c \Delta T = \frac{\nu_1}{\delta_1} \Delta T
\]

the heat transfer coefficient \( h_c \) is given by the following expression

\[
h_c = \left\{ \frac{870 \xi}{65.76 - 3.26 (1 - N_q)[1 - N_q]} \right\}^{1/2} \frac{\mu_{1} K_{1} \Delta T}{\rho_{1} \Delta t \sqrt{g(\rho_2 - \rho_1)}} \right\}^{1/4}
\]

where \( \xi \) must still be determined, which is done as follows. This heat transfer coefficient although derived for the film boiling region must also be valid at the minimum heat flux where it takes the value of \( h_c \text{ min} \). On the other hand, we can calculate a heat transfer coefficient \( h_c \text{ min} \) from our theoretical expression of \( q \text{ min} \), given by equation (63), by:

\[
\frac{h_c \text{ min}}{\Delta T} = \frac{\text{q min}}{\Delta T}
\]
Applying this to water and equating the two gives a numerical value of $\xi$ which can then be introduced in equation (78) to yield:

$$h_c = \left\{ \frac{[65.76-3.26(1-N_q)][1-N_q]}{5.417} \right\}^{1/2} \left\{ \frac{K_1^3 \rho_1 \Delta t \Delta g(\rho_2-\rho_1)}{\mu_1 \Delta T \sqrt{\sigma}} \right\}^{1/4} \tag{79}$$

This final expression of the heat transfer coefficient in the film boiling region can be expressed in a non-dimensional form:

$$h_c^+ = \left\{ \frac{[65.76-3.26(1-N_q)][1-N_q]}{5.417} \right\}^{1/2} \left\{ \frac{K_1^3 \rho_1 \Delta t \Delta g(\rho_2-\rho_1)}{\mu_1 \Delta T \sqrt{\sigma}} \right\}^{1/4} \tag{80}$$

where $h_c^+$ the dimensionless heat transfer coefficient is obtained by

$$h_c^+ = \frac{h_c}{\left\{ \frac{K_1^3 \rho_1 \Delta t \Delta g(\rho_2-\rho_1)}{\mu_1 \Delta T \sqrt{\sigma}} \right\}^{1/4}}$$

In equation (79) or (80), due to its exponent, the $N_q$ term does not affect very much the value of the heat transfer coefficient as long as $N_q$ is much smaller than unity. As it becomes comparable to one (which can be realized at high pressures or extremely high heat fluxes),
it contributes to decrease the heat transfer coefficient which is in concordance with the experimental results of Abadzic and Goldstein [2]. Furthermore, the value of unity for $N_q$ which would cancel the expression of the heat transfer coefficient is not acceptable. Indeed our model is limited to the case where $N_q$ equals one (See Chapter III, Section 3). Therefore, by equation (69), $N_q$ cannot reach the value of unity without being outside of the domain of validity of the expressions.

This analytical result for the heat transfer coefficient is now compared with the experiments of Hosier and Westwater [8] at atmospheric pressure in the vicinity of the minimum heat flux (moderate $\Delta T$).

<table>
<thead>
<tr>
<th>Nature of Fluid</th>
<th>$\Delta T$ ($^\circ F$)</th>
<th>$h_c^+$ From Analysis</th>
<th>$h_c^+$ From Experiments [8]</th>
</tr>
</thead>
<tbody>
<tr>
<td>Water</td>
<td>285</td>
<td>0.519</td>
<td>0.56</td>
</tr>
<tr>
<td>Water</td>
<td>345</td>
<td>0.519</td>
<td>0.55</td>
</tr>
<tr>
<td>Water</td>
<td>385</td>
<td>0.519</td>
<td>0.54</td>
</tr>
<tr>
<td>Freon 11</td>
<td>220</td>
<td>0.519</td>
<td>0.53</td>
</tr>
<tr>
<td>Freon 11</td>
<td>280</td>
<td>0.519</td>
<td>0.5</td>
</tr>
<tr>
<td>Freon 11</td>
<td>375</td>
<td>0.517</td>
<td>0.5</td>
</tr>
</tbody>
</table>

The good agreement between the theory and the experiments can be seen. This is confirmed at higher heat fluxes and temperature differ-
ence as it is shown in the following table.

Sauer and Ragsdell [27] performed experiments of film boiling of nitrogen on a flat horizontal two inches heater. They obtained data for temperature differences as high as $1250^\circ F$ where there is a radiative contribution to the total heat flux. By deducing this contribution from their measurements they propose results where the radiation is not included which is exactly what is done in this analysis of the heat transfer coefficient $h_c$. The comparison is thus adequate and presented here.

<table>
<thead>
<tr>
<th>Nature of Fluid</th>
<th>$\Delta T$ ($^\circ F$)</th>
<th>$h_c^+$ From Analysis</th>
<th>$h_c^+$ From Experiments [27]</th>
</tr>
</thead>
<tbody>
<tr>
<td>Nitrogen</td>
<td>500</td>
<td>0.51</td>
<td>0.52</td>
</tr>
<tr>
<td>Nitrogen</td>
<td>200</td>
<td>0.504</td>
<td>0.49</td>
</tr>
<tr>
<td>Nitrogen</td>
<td>1250</td>
<td>0.489</td>
<td>0.47</td>
</tr>
</tbody>
</table>

In Figures 7 to 12 the above comparisons are expressed in terms of dimensional heat fluxes and heat transfer coefficients.

In all the instances the agreement between the theory and the experiments is seen to be good, and therefore the proposed heat transfer coefficient is recommended for pool film boiling on horizontal flat surfaces.
Figure 7. Heat Transfer Coefficient Versus Temperature Difference for Water.
\[ q_c \times 10^4 \left( \frac{\text{BTU}}{h \text{ ft}^2} \right) \]

Figure 8. Heat Flux Versus Temperature Difference for Water.
Figure 9. Heat Transfer Coefficient Versus Temperature Difference for Freon 11.
Figure 10. Heat Flux Versus Temperature Difference for Freon 11.
Figure 11. Heat Transfer Coefficient Versus Temperature Difference for Nitrogen.
Figure 12. Heat Flux Versus Temperature Difference for Nitrogen.
CHAPTER VI

CONCLUSION

Pool film boiling from a flat horizontal surface has been studied analytically and the results are in good agreement with the experimental data available in the literature.

In a three-dimensional model, the wave velocity at the interface between two heated superposed fluids of finite depths has been first derived and is given by equation (37).

The analysis of the interface stability is then applied to the minimum heat flux and the film boiling region. In contrast to gravity, the mass transfer and the surface tension appear to have a stabilizing influence.

The three-dimensional treatment of the problem is more adequate than the usual two-dimensional approach to predict the flow pattern:

(a) the average interbubble distance varies between two values: the critical and most dangerous wavelengths given by equations (44) and (52) where the effect of the interfacial mass transfer appears explicitly.

(b) the average bubble diameter at breakoff is $1/\sqrt{2}$ times that distance

(c) the bubble diameter and the frequency of bubble release given by equation (60) agree very closely with the experimental measurements from a flat surface.
At high pressures, the modification of the boiling pattern can now be predicted theoretically. The change from a regularly bubbling interface to a large vapor sheet covering the heated surface happens when the non-dimensional term \( M_q \), which scales the mass transfer and the gravity effects, equals unity.

At low pressure, however, for most of the fluids, the \( M_q \) term approaches unity only at extremely high values of the heat flux; and, therefore, the film boiling pattern keeps its rather regular characteristics up to very high temperature differences. This explains why the insertion of the mass transfer in the equation giving the minimum heat flux, that is, equation (63) brings little change in the actual value in comparison with the traditional relationships presented in the literature. The same holds to a smaller extent for the film boiling heat transfer coefficient whose expression, as given in equation (69), is also significantly influenced by the interfacial mass transfer only at very high temperatures.

Finally, a recommendation for further investigations can be proposed and this involves the carrying out of experiments of film boiling on a large flat horizontal surface at low pressures and high heat fluxes as well as at high pressures.
BIBLIOGRAPHY


