

Substrate-Embedded and Flip-Chip-Bonded Photodetector Polymer-Based Optical Interconnects: Analysis, Design, and Performance

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Abstract—The performance of three optoelectronic structures incorporating substrate-embedded InP-based inverted metal–semiconductor–metal photodetectors and/or volume holographic gratings are analyzed and compared at the primary optical communication wavelengths. These structures, in conjunction with optical-quality polymer layers, can be easily integrated into silicon microelectronic substrates for the purpose of implementing potentially low-cost high-data-rate chip-level or substrate-level optical interconnects. The structures are as follows: a) an evanescent-coupling architecture with a substrate-embedded photodetector, b) a volume-holographic-grating coupler architecture with a substrate-embedded photodetector, and c) a volume-holographic-grating coupler architecture with a flip-chip-bonded photodetector. It is found that the primary characteristic of the evanescent coupling architectures is the efficient performance for both TE and TM polarizations with the disadvantage of exponentially decreasing efficiency with increasing separation between the waveguide film layer and the photodetector layer. On the other hand, the primary characteristic of the volume holographic grating architectures is the possibility of wavelength and polarization selectivity and their independence on the separation between the photodetector layer and the waveguide. Comparison of the analysis with experimental results is also included in the case of the evanescent coupling into a substrate-embedded photodetector.

Index Terms—Electromagnetic coupling, electromagnetic radiation, gratings, optical couplers, optical interconnections, packaging, photodetectors.

I. INTRODUCTION

As electronic system aggregate data rates rise and the sizes decrease, conventional electrical interconnections face multiple challenges at the backplane, board, and module levels. High-performance electrical interconnection systems inevitably trade off power consumption, area, and signal integrity (jitter, delay, skew). Architectural and design approaches, as well as technological innovation at the physical layer level, can be used to improve interconnection performance. However, physical limitations will ultimately force technology changes

at the physical layer if performance gains are to continue well into the future. If low loss, high-speed, low-power, compact optical interconnections could be implemented at the board and module levels with simple interfaces, this could offer the designer a high-performance interconnect option in a relatively inexpensive board technology.

A number of quantitative comparisons of interconnection performance have been published discussing electrical and optical interconnections [1]–[3]. A critical issue is how to integrate optical interconnections into an electrical interconnection system. Optical interconnect approaches include free-space interconnects with diffractive optical elements [4], silicon optical bench interconnects [5], and guided-wave interconnections, including substrate-guided-mode interconnects [6], fiber-optic waveguides [7], and integrated waveguides [8]. This paper focuses on waveguide optical interconnections that are integrated directly onto the electrical interconnection package media such as boards and modules.

Electrical boards, modules, and integrated circuits are essentially planar, and thus, an embedded planar waveguide optical interconnection scheme matches the topography of the electrical system. One basic classification of waveguide optical interconnections embedded in a board is whether or not the optical beam is turned perpendicular to the waveguiding plane for electrical-to-optical and optical-to-electrical conversion interfaces. Mirrors (that represent localized-type coupling) and gratings (that represent distributed-type coupling) can be used to turn the optical beam to/from the waveguide into optoelectronic emission/detection devices. However, mirrors have the disadvantage of alignment sensitivity due to their localized-type coupling. On the other hand, gratings represent a distributed-type coupling and therefore can be more alignment tolerant. Gratings could be either of volume-holographic type or of surface-relief type. Furthermore, to achieve preferential coupling (toward a desired direction), slanted gratings need to be utilized. The slant does not complicate the fabrication process of the volume holographic gratings. However, slanted surface-relief gratings are generally difficult to fabricate especially in large areas and in multiple locations. Alternatively, emitters and detectors can be embedded in the waveguide using heterogeneous integration or monomaterial substrate/device integration. For example, silicon metal–semiconductor–metal (MSM) photodetectors have been proposed for embedded implementation of optical interconnects

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using beam turning elements such as slanted surface-relief gratings and 45° micromirrors [9]. However, silicon MSM photodetectors are not as efficient as the InP-material-based inverted MSM photodetectors. Another advantage of the InP-material-based photodetectors is that their carrier lifetime is generally shorter thus permitting higher data-rate implementations.

In this paper, potentially low-cost fully substrate-embedded or flip-chip bonded optical interconnect architectures are analyzed and compared at the main optical communication wavelengths ($1.3 \mu\text{m}$ and $1.55 \mu\text{m}$). The architectures involve a volume-holographic grating coupling for beam turning or/and an embedded thin-film inverted-MSM photodetector for evanescent coupling. The architectures can be integrated on silicon microelectronic substrates with InP-material-based thin-film photodetectors and optical quality polymer layers that can be used as waveguides and/or volume holographic gratings. Three structures are explored as follows: a) an evanescent-coupling architecture with a substrate-embedded photodetector, b) a volume-holographic-grating coupler architecture with a substrate-embedded photodetector, and c) a volume-holographic-grating coupler architecture with a flip-chip-bonded photodetector. The customized volume-holographic gratings are recorded in photosensitive polymers such as the DuPont OmniDex613 (HRF600X) and can be laminated on top of a waveguide. All architectures are analyzed, optimized, and compared. Their primary characteristics are investigated as well as their advantages and disadvantages. The analysis of the three proposed architectures is presented in Section II. The design and optimization of the architectures are presented in Section III. Some fabrication issues are summarized in Section IV. Some preliminary experimental results are presented in Section V. Finally, the summary and the main conclusions of this paper are given in Section VI.

II. ANALYSIS OF PROPOSED STRUCTURES

The basic waveguiding structure is composed of a single-mode slab waveguide, as shown to the left of the x -axis in Fig. 1(a)–(c). The waveguide film layer has an index of refraction n_f and a thickness t_2 . The cover and the substrate are considered semi-infinite regions with refractive indexes n_c and n_s , respectively. In Fig. 1(a)–(c), three structures are shown: in (a), an evanescent-coupling architecture with a substrate-embedded photodetector, in (b), a holographic grating coupler architecture with a substrate-embedded photodetector, and in (c), a holographic grating coupler architecture with a flip-chip-bonded photodetector. The objective of all of these architectures is the coupling of guided light incident from the left to the photodetector (either substrate embedded or flip-chip bonded) that is represented by the semi-infinite layer of refractive index n_D . In general, the photodetector region has a finite thickness (thin-film photodetector) and a complex refractive index representing the absorption of the optical power. However, for simplicity in this analysis, the photodetector region is modeled by a semi-infinite region since any optical power that enters this region does not return to the waveguide due to absorption. As a result, the finite-thickness photodetector region of complex refractive index can be simplified and be

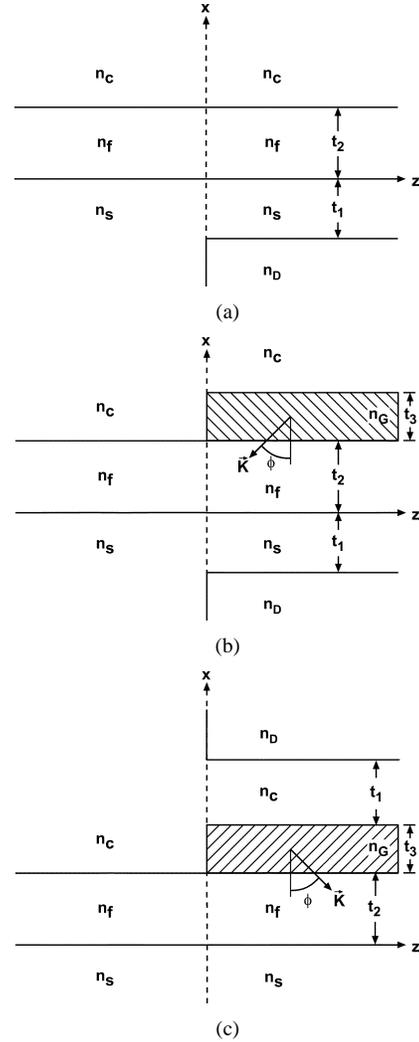


Fig. 1. (a) The geometry of evanescent coupling to the substrate-embedded photodetector. The single-mode optical waveguide has a thickness of t_2 and refractive indexes of n_c , n_f , and n_s for the cover, film, and substrate layers, respectively. The embedded photodetector region starts at $z > 0$, and the photodetector layer is at a distance t_1 from the film layer and has a refractive index $n_D > n_f > n_s > n_c$. (b) The geometry of holographic-grating coupling to the substrate-embedded photodetector. The single-mode waveguide and the embedded photodetector have the same parameters as in (a). The holographic grating extends from $z > 0$ and has a thickness of t_3 and an average refractive index of n_G . The grating vector \vec{K} and its slant angle ϕ are also shown. (c) The geometry of holographic-grating coupling to the flip-chip-bonded photodetector. All parameters are similar to those in (b).

represented by a semi-infinite region of real refractive index n_D . It is assumed that a single mode (TE or TM polarized) with optical power P_{inc} is propagating in the slab waveguide from left to right. The theoretical models for the analysis and performance evaluation of all architectures are summarized next.

A. Evanescent Coupling From Waveguide to Substrate-Embedded Photodetector

The evanescent coupling architecture is shown in Fig. 1(a). The substrate-embedded photodetector is placed at a distance t_1 from the film layer of the waveguide (region of $z > 0$). The refractive index of the photodetector (InP-based material system) is assumed to be larger than any of the surrounding indexes, i.e.,

$n_D > n_f > n_s > n_c$. Therefore, when guided light enters the region of the embedded photodetector ($z > 0$), the evanescent tail (toward the substrate) of the guided mode “senses” the presence of the high index region of the photodetector because of the frustrated total internal reflection at the film-substrate boundary. As a result, and assuming that t_1 is on the order of the light wavelength, the optical power from the guided mode radiates into the embedded photodetector region, where it is absorbed and produces a photocurrent. Thus, the optical signal transferred by the optical waveguide mode is being converted into an electrical signal that is transmitted via the photodetector circuitry to the electronic components of the substrate.

The radiation (leakage) of the guided-mode power in region $z > 0$ can be represented using a leaky-mode description of the electromagnetic field [10], [11]. Under the leaky-mode description, the electromagnetic field in the waveguide for $z > 0$ can be manifested by a complex propagation constant $\tilde{\beta} = \beta - j\alpha$, and the optical field $U(x, z)$ (electric or magnetic) can be expressed as $U(x, z) = U(x) \exp(-j\tilde{\beta}z) = U(x) \exp(-j\beta z) \exp(-\alpha z)$, where $U(x)$ corresponds to the field profile along the x direction. The optical power $P(z)$ that is radiated and absorbed into the embedded detector region can then be expressed as

$$P(z) = (1 - R)P_{\text{inc}}(1 - e^{-2\alpha z}) \quad (1)$$

where R represents the percentage of the reflected power of the incident mode when it enters the photodetector ($z > 0$) region. The reflected power RP_{inc} depends on the separation t_1 between the film layer and the photodetector layer. It is expected that the smaller t_1 is, the stronger the radiation and, consequently, the absorption of the optical power in the photodetector would be. However, the smaller t_1 is, the stronger the discontinuity at the $z = 0$ interface becomes, thus resulting in higher reflection losses of the incident mode (larger R). Therefore, there is an optimal separation t_1 between the film layer and the photodetector layer that will maximize the power $P(z = L)$ for a given detector layer length (along the z -axis) L . The imaginary part α of the complex propagation constant of the leaky mode can be defined as the *radiation coupling coefficient* since the leakage of the mode represents the power radiated into the photodetector area. The power that can radiate into the cover (air) area (for $z > 0$) can be neglected since those leaky modes will not be strongly excited at the $z = 0$ interface. The radiation coupling coefficient α can be calculated using the argument principle method (APM) [12], [13]. The latter method is a rigorous mathematical technique based on complex analysis [14] and is capable of finding the zeros (leaky-mode propagation constants $\tilde{\beta} = \beta - j\alpha$) of any analytic function (the waveguide dispersion relation) in the complex plane. Therefore, the radiation coupling coefficient α in (1) can be easily determined. However, the APM method cannot be used for the estimation of the percentage of the reflected power R . In order to calculate R , the finite-difference frequency-domain (FDFD) method is used [15]–[17] in conjunction with Bérenger’s perfectly matched layer and absorbing boundary conditions [18]. With α and R calculated using the APM and FDFD methods,

respectively, the power absorbed in the detector area as well the optimal selection of t_1 can be determined.

B. Holographic-Grating Coupling From Waveguide to Substrate-Embedded Photodetector

The holographic-grating architecture for coupling from the waveguide to the substrate-embedded photodetector is shown in Fig. 1(b). The embedded photodetector is placed again at a distance t_1 from the film layer of the waveguide (region of $z > 0$) and has similar parameters as in the evanescent coupling architecture. The holographic grating (usually composed of a photopolymer) is on the top of the waveguide for $z > 0$. The average refractive index of the grating is n_G , while the grating vector is defined as $\vec{K} = K_x\hat{x} + K_z\hat{z} = -(2\pi/\Lambda)(\hat{x}\cos\phi + \hat{z}\sin\phi)$, with ϕ being the slant angle ($0 < \phi < 90^\circ$), Λ the period of the holographic grating, and \hat{x} , \hat{z} corresponding to the unit vectors along the x and z directions, respectively. In order for the incident-from-the-left guided mode to remain guided in the $z > 0$ region, it is assumed that t_1 is several wavelengths long so that the frustrated total internal reflection at the film-substrate boundary can be neglected and that $n_G < n_f$. Therefore, when guided light enters the region of the embedded photodetector ($z > 0$), the evanescent tail (in this case toward the cover) of the guided mode “senses” the presence of the periodic index modulation of the holographic grating region. As a result, optical power from the guided mode can get diffracted preferentially toward the embedded photodetector region, where it is absorbed and produces a photocurrent as in the evanescent coupling architecture of Fig. 1(a). Thus, in the holographic-grating coupling architecture, the optical signal transferred by the optical waveguide mode is being converted into an electrical signal that is transmitted via the photodetector circuitry to the electronic components of the substrate. The major difference relative to the evanescent-coupling architecture is that the grating could have wavelength- and polarization-sensitive (to the incident mode) performance in contrast to the evanescent-coupling architecture.

The holographic grating has a relative permittivity variation ε_G expressed by

$$\begin{aligned} \varepsilon_G(x, z) &= n_G^2 + \varepsilon_1 \cos(\vec{K} \cdot \vec{r}) \\ &= n_G^2 + \varepsilon_1 \cos(K_x x + K_z z) \end{aligned} \quad (2)$$

where ε_1 is the grating modulation and $\vec{r} = x\hat{x} + y\hat{y} + z\hat{z}$. A higher number of harmonics can be easily added in the above expression without affecting the analysis presented below. However, for holographic gratings, a sinusoidally varying relative permittivity expresses reliably the grating modulation in most cases. When the guided mode enters the region of the embedded photodetector ($z > 0$), electromagnetic power diffracts toward the photodetector region where it is absorbed. The diffraction (leakage) of the power of the mode in the region with $z > 0$ can be represented again by a leaky-mode description of the electromagnetic field in this region [19]–[24]. Under the leaky-mode description, the electromagnetic field in the $z > 0$ region can be represented by the complex propagation constant $\tilde{\beta} = \beta - j\alpha$

and the optical field in each layer (electric or magnetic for TE or TM polarization respectively) can be expressed according to the rigorous coupled-wave analysis [25], [26] as

$$\begin{aligned} U_m(x, z) &= \hat{y} \sum_i S_{mi}(x) \exp(ji\vec{K} \cdot \vec{r}) \exp(-j\tilde{\beta}z) \\ &= \hat{y} \sum_i S_{mi}(x) \exp[ji(K_x x + K_z z)] \\ &\quad \times \exp(-j\beta z) \exp(-\alpha z) \end{aligned} \quad (3)$$

where m corresponds to the grating layer (of thickness t_3), to the waveguide film layer (of thickness t_2), or to the substrate layer (of thickness t_1); S_{mi} are the spatial harmonics in each layer; and i corresponds to the number of the diffracted orders that are retained in the analysis. The fields in the cover and photodetector regions can be expressed as

$$U_c(x, z) = \hat{y} \sum_i R_i \exp(-j\vec{k}_{ci} \cdot \vec{r}) \quad (4)$$

$$U_D(x, z) = \hat{y} \sum_i T_i \exp(-j\vec{k}_{Di} \cdot \vec{r}) \quad (5)$$

where R_i and T_i are the amplitudes of the diffracted waves in the cover and photodetector regions, respectively. The wavevectors $\vec{k}_{ci} = (\tilde{\beta} - iK_z)\hat{z} + k_{cxi}\hat{x}$ and $\vec{k}_{Di} = (\tilde{\beta} - iK_z)\hat{z} + k_{Dxi}\hat{x}$ correspond to the wavevectors for each diffracted order i in the cover and photodetector regions, respectively. The x -components of the wavevectors k_{cxi} and k_{Dxi} can be determined from the plane-wave dispersion relations $k_{\ell xi}^2 + k_{\ell zi}^2 = k_0^2 n_\ell^2$ (with $\ell = c$ or D). Furthermore, due to the complex propagation constant $\tilde{\beta}$, the x components k_{cxi} and k_{Dxi} of the diffracted wavevectors have to be selected appropriately [23], [24], [27] in order to correspond to physical radiation directions of the diffracted fields. Using the electric and magnetic field components of the optical waves in the various regions in conjunction with the electromagnetic boundary conditions and taking into account the rigorous coupled-wave analysis solution method, the complex propagation constant $\tilde{\beta}$ can be determined as a solution of a transcendental equation $\det[\mathbf{M}(\tilde{\beta})] = 0$, where \mathbf{M} is a matrix of size $8N \times 8N$ and N is the number of diffracted orders retained in the analysis.

After the calculation of $\tilde{\beta}$, the optical power $P(z)$ that is diffracted and absorbed in the embedded detector region can then be expressed by

$$P(z) = (1 - R)\eta_D P_{\text{inc}}(1 - e^{-2\alpha z}) \quad (6)$$

where R again represents the percentage of the reflected power of the incident mode when it enters the photodetector ($z > 0$) region and η_D is the preferential coupling ratio [22]–[24] that is defined as the fraction of the total power that is diffracted into the photodetector region. As in the evanescent coupling architecture, the reflected power RP_{inc} depends strongly (exponentially) on the separation t_1 between the film layer and the photodetector layer. However, in this case t_1 should be selected several wavelengths in length; otherwise (as will be shown in Section III) the evanescent coupling prevails as compared to the holographic-grating coupling. Therefore, with this selection of t_1 , the effect of the reflection at $z = 0$ becomes small since the power reflected would depend only on the presence of the grating layer, which has a much smaller refractive index

mismatch. With α and η_D calculated using the rigorous coupled-wave analysis, and R using the FDFD method, the power absorbed in the detector area can be calculated as a function of the coupler length and can also be compared to the power coupled using the evanescent coupling architecture.

C. Holographic-Grating Coupling From Waveguide to Flip-Chip-Bonded Photodetector

The holographic-grating architecture for coupling from the waveguide to the flip-chip-bonded photodetector is shown in Fig. 1(c). In this architecture, the photodetector is placed at a distance t_1 , which is large in comparison to the optical wavelength due to the flip-chip bonding bumps (on the order of 50 μm). Therefore, no evanescent coupling between the waveguide and the detector layers exists. The coupling in this case is solely provided by the grating, which in this case is designed to diffract power in the positive x -direction. The grating vector in this case is defined as (in order to have $0 < \phi < 90^\circ$ as before) $\vec{K} = K_x \hat{x} + K_z \hat{z} = (2\pi/\Lambda)(-\hat{x} \cos \phi + \hat{z} \sin \phi)$, with ϕ being the slant angle and Λ the period of the holographic grating as before. The analysis of this architecture is very similar to that of grating coupling to the substrate-embedded photodetector presented in the previous section. The only difference is that (3) now holds for the grating region (of thickness t_3), the cover region (of thickness t_1), and the film region (of thickness t_2). In addition, the fields in photodetector and substrate regions can be expressed as

$$U_D(x, z) = \hat{y} \sum_i R_i \exp(-j\vec{k}_{Di} \cdot \vec{r}) \quad (7)$$

$$U_s(x, z) = \hat{y} \sum_i T_i \exp(-j\vec{k}_{si} \cdot \vec{r}) \quad (8)$$

where R_i and T_i are the amplitudes of the diffracted waves in the photodetector and substrate regions, respectively. The wavevectors $\vec{k}_{Di} = (\tilde{\beta} - iK_z)\hat{z} + k_{Dxi}\hat{x}$ and $\vec{k}_{si} = (\tilde{\beta} - iK_z)\hat{z} + k_{sxi}\hat{x}$ correspond to the wavevectors for each diffracted order i in the photodetector and substrate regions, respectively. The k_{Dxi} and k_{sxi} components can be determined from the plane-wave dispersion relations similarly to the procedure described in the previous section. The rigorous coupled-wave analysis in conjunction with the leaky-mode field description is used again for the determination of the power that is coupled into the photodetector region. This power can be expressed again by (6).

III. DESIGN AND OPTIMIZATION OF COUPLING STRUCTURES

The parameters used for the implementation of the architectures shown in Fig. 1(a)–(c) are based on polymer materials and for the primary telecommunications wavelengths, i.e., $\lambda_0 = 1.3$ and 1.55 μm . For example, for the substrate-embedded-photodetector architectures [Fig. 1(a) and (b)], the film layer is composed of *Utem* polymer [28] of refractive index $n_f = 1.65$. In the latter cases, the substrate material is comprised of benzocyclobutane (BCB) polymer [29] of refractive index $n_s = 1.55$. In the case of the flip-chip-bonded-photodetector architecture [Fig. 1(c)], the waveguide material is BCB of $n_f = 1.55$ and the substrate material is SiO_2 of $n_s = 1.45$. The photodetector layer is composed of a InP-based material and has an average

refractive index $n_D = 3.7$. The cover area is assumed to be air ($n_c = 1.0$). The holographic grating is recorded in the DuPont photopolymer OmniDex613 (HRF600X) of a refractive index $n_G = 1.50$. The photopolymer is available in laminating sheets of thickness $t_3 = 10 \mu\text{m}$ after the removal of the Mylar protective layers. Therefore, the thickness of the photopolymer is always taken to be $10 \mu\text{m}$. For all grating designs, it was assumed that the refractive index modulation is $\varepsilon_1 = 2n_G\Delta n$ with $\Delta n = 0.02$, which corresponds to the photopolymer used. The waveguide is designed to be single-mode for both wavelengths of interest. The separation t_1 between film and photodetector layers varies depending on the architecture under investigation.

A. Evanescent Coupling of Waveguide to Substrate-Embedded Photodetector

In the case of the evanescent coupling architecture, it is very important to determine the optimal separation of film and photodetector layers in order to maximize the power that can be absorbed [in (1), both α and R depend on t_1]. For this reason, the percentage of the reflected power $P_{\text{refl}} = R$ needs to be determined as a function of t_1 for both wavelengths of interest ($\lambda_0 = 1.3$ and $1.55 \mu\text{m}$) and for both incident polarizations (TE or TM incident mode). As was discussed in previous sections, the FDFD method was employed for this calculation. The waveguide film layer thickness was selected to be $t_2 = 1.0 \mu\text{m}$ in this case. For the FDFD numerical implementation, the structure was enclosed around the $z = 0$ interface in a computational box [17] of size $2 \mu\text{m}$ along the z -direction and $13\text{--}15 \mu\text{m}$ along the x -direction including an absorbing boundary layer $2\text{--}3 \mu\text{m}$ thick. The grid point separation was $\lambda_0/20n_{\text{max}}$ or smaller where n_{max} is the maximum refractive index (in this case $n_{\text{max}} = n_D = 3.7$). The incident mode was the TE_0 or the TM_0 of the single-mode waveguide. The FDFD method gives the complete electromagnetic field description. For example, in Fig. 2(a) and (b), the electric field intensity ($|U|^2 = |E_y|^2$) and the magnetic field intensity ($|U|^2 = |H_y|^2$) are shown for TE_0 and TM_0 incident modes, respectively, for $t_1 = 0 \mu\text{m}$ and $\lambda_0 = 1.3 \mu\text{m}$. In these figures the absorbing regions of the computational box are not shown since these regions do not correspond to the real structure but are used merely to absorb the power radiating away from the structure [17]. The dark regions represent areas of high field (electric or magnetic) intensity ($|E_y|^2$ or $|H_y|^2$). The boundaries between various regions and the refractive indexes are also shown to facilitate understanding. The presence of the high index photodetector layer causes reflection losses at the $z = 0$ plane. The interference maxima and minima can be seen in the waveguide film layer for both cases, as well as the radiation into the photodetector layer. Using discrete Fourier transforms of the electromagnetic fields [17], it is possible to determine the percentage of the reflected power as a function of t_1 . The percentage of the reflected power $P_{\text{refl}} = R$ is shown in Fig. 3 as function of t_1 for both TE_0 and TM_0 incident guided modes and for both $\lambda_0 = 1.3 \mu\text{m}$ and $\lambda_0 = 1.55 \mu\text{m}$ free-space wavelengths. From this figure it can be seen that the reflected power depends exponentially on t_1 and is negligible for detector-waveguide separations $t_1 > 2 \mu\text{m}$.

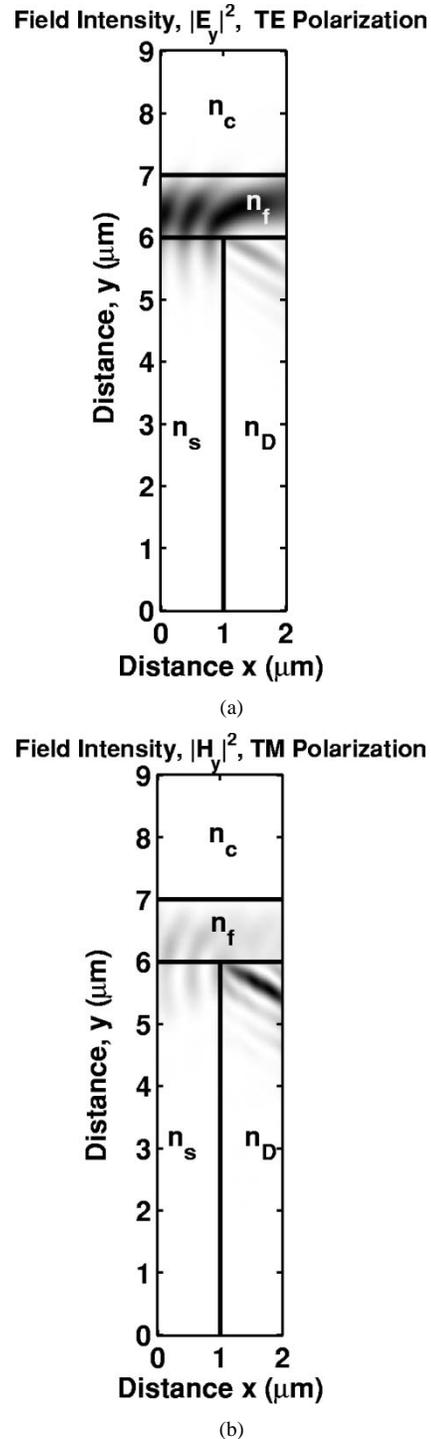


Fig. 2. (a) The electric field intensity pattern $|E_y|^2$ for a TE_0 incident mode. The mode is propagating from left to right and is incident on the $z = 0$ waveguide discontinuity (due to the presence of the photodetector layer, with $t_1 = 0$). The dark regions represent areas of high electric field intensity. The boundaries between various regions and the refractive indexes are also shown. The free-space wavelength of the light is $1.3 \mu\text{m}$. This is a special case of Fig. 1(a) for $t_1 = 0$. (b) Same as in (a) but the magnetic field intensity $|H_y|^2$ is shown for a TM_0 incident mode.

Using the APM method [12], the radiation coupling coefficient α can also be determined. This is shown in Fig. 4 as a function of the separation distance t_1 (between waveguide and photodetector) for both TE_0 and TM_0 incident polarizations and for both $\lambda_0 = 1.3 \mu\text{m}$ and $\lambda_0 = 1.55 \mu\text{m}$ free-space wavelengths.

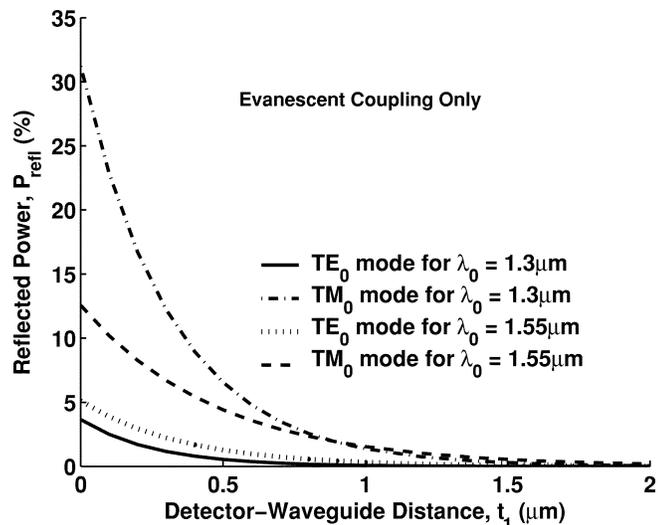


Fig. 3. Percentage of reflected power $P_{\text{refl}} = R$ at the $z = 0$ waveguide discontinuity as a function of detector-waveguide (film) distance t_1 for the case of the evanescent coupling architecture. The various line types show the normalized reflected power P_{refl} for both TE_0 and TM_0 incident modes as well as for $\lambda_0 = 1.3$ and $1.55 \mu\text{m}$ free-space wavelengths.

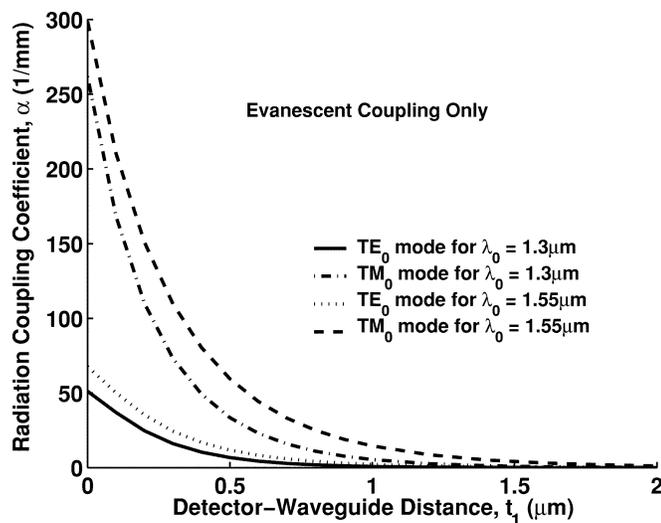
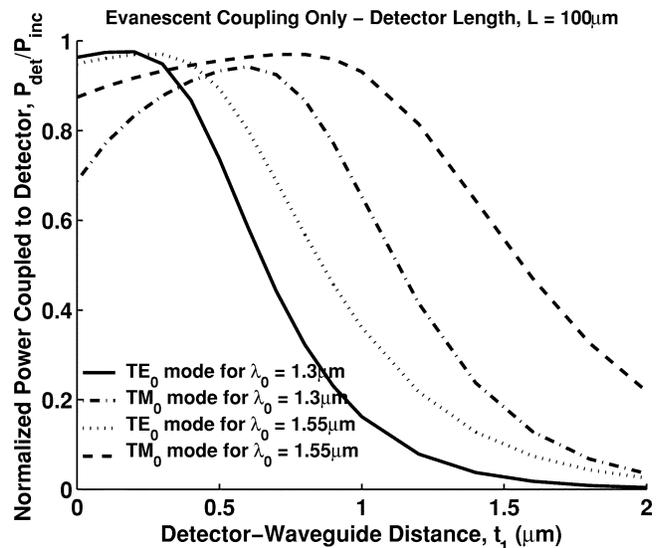


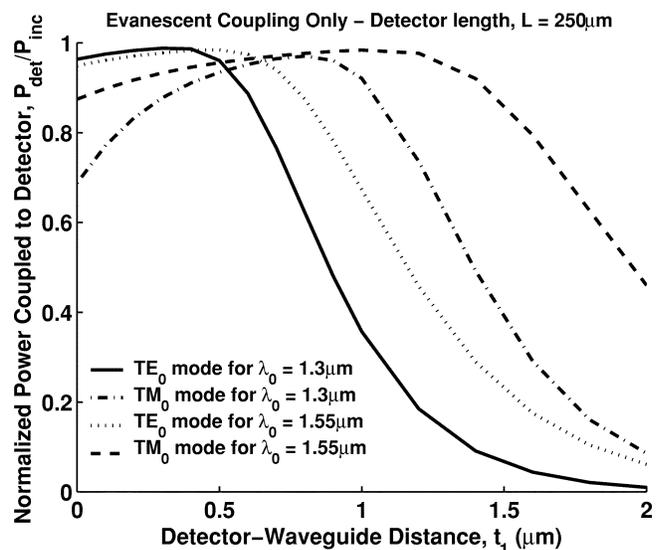
Fig. 4. Radiation coupling coefficient α for the leaky waveguide formed in the region $z > 0$ as a function of detector-waveguide (film) distance t_1 for the case of the evanescent coupling architecture. The various line types show the radiation coupling coefficient α for both TE_0 and TM_0 incident modes as well as for $\lambda_0 = 1.3$ and $1.55 \mu\text{m}$ free-space wavelengths.

From Fig. 4, it can also be seen that the radiation coupling coefficient reduces exponentially as the separation distance between detector and waveguide increases. This means that the presence of the photodetector layer will not cause the guided light to radiate (“leak”) into the photodetector layer for large t_1 .

The total normalized power that is coupled into the photodetector layer $P_{\text{det}}/P_{\text{inc}} = P(z = L)/P_{\text{inc}}$, where $P(z)$ is given by (1) and L is the length (along the z -direction) of the photodetector, is shown in Fig. 5(a) and (b) as a function of the separation t_1 for $L = 100$ and $250 \mu\text{m}$, respectively, for both TE_0 and TM_0 incident polarizations and for both $\lambda_0 = 1.3$ and $1.55 \mu\text{m}$ free-space wavelengths. From these figures, it can be seen that



(a)



(b)

Fig. 5. Normalized power coupled to the detector $P_{\text{det}}/P_{\text{inc}} = P(z = L)/P_{\text{inc}}$ for the leaky waveguide formed in the region $z > 0$ as a function of detector-waveguide (film) distance t_1 for the case of the evanescent coupling architecture. The various line types show the normalized power $P_{\text{det}}/P_{\text{inc}}$ for both TE_0 and TM_0 incident modes as well as for $\lambda_0 = 1.3$ and $1.55 \mu\text{m}$ free-space wavelengths. (a) For detector length $L = 100 \mu\text{m}$ and (b) for detector length $L = 250 \mu\text{m}$.

TABLE I

OPTIMAL SEPARATION t_1 (IN μm) BETWEEN WAVEGUIDE FILM LAYER AND PHOTODETECTOR LAYER IN THE EVANESCENT COUPLING ARCHITECTURE FOR BOTH TE_0 AND TM_0 INCIDENT MODES AND FOR $\lambda_0 = 1.3 \mu\text{m}$ AND $1.5 \mu\text{m}$ FREE-SPACE WAVELENGTHS AND $L = 100$ AND $250 \mu\text{m}$. ALL t_1 SEPARATIONS ARE ROUNDED TO A TENTH OF A MICROMETER

	$L = 100 \mu\text{m}$		$L = 250 \mu\text{m}$	
	$\lambda_0 = 1.3 \mu\text{m}$	$\lambda_0 = 1.55 \mu\text{m}$	$\lambda_0 = 1.3 \mu\text{m}$	$\lambda_0 = 1.55 \mu\text{m}$
TE_0	0.3	0.4	0.4	0.5
TM_0	0.6	0.8	0.9	1.0

there is an optimal separation t_1 for a given detector length, incident mode polarization, and wavelength. The optimal separations are summarized in Table I for the abovementioned two

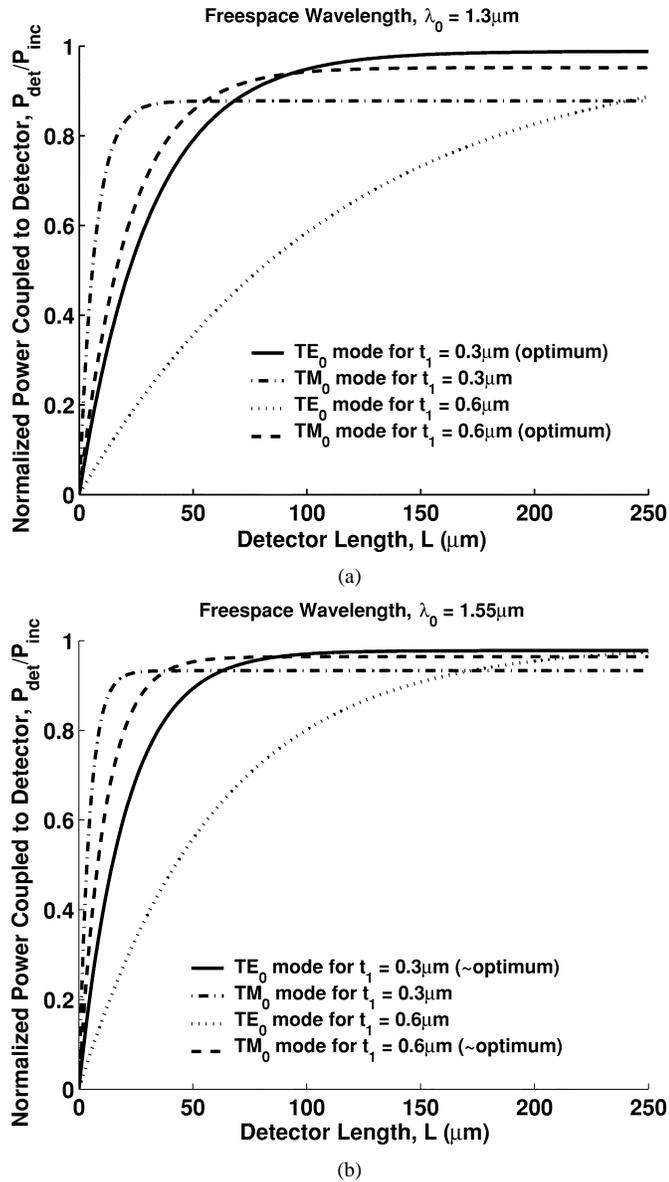


Fig. 6. Normalized power coupled to the detector $P_{\text{det}}/P_{\text{inc}} = P(z = L)/P_{\text{inc}}$ for the leaky waveguide formed in the region $z > 0$ as a function of the detector length for the case of the evanescent coupling architecture. The various line types show the normalized power $P_{\text{det}}/P_{\text{inc}}$ for both TE₀ and TM₀ incident modes as well as for optimal, near optimal, and nonoptimal t_1 separation. (a) For free-space wavelength $\lambda_0 = 1.3 \mu\text{m}$. For this wavelength the optimal t_1 values from Table I are for the TE₀ mode $t_1 = 0.3 \mu\text{m}$ and for the TM₀ mode $t_1 = 0.60 \mu\text{m}$. (b) For free-space wavelength $\lambda_0 = 1.55 \mu\text{m}$ using the optimal separations t_1 specified for the $\lambda_0 = 1.3 \mu\text{m}$ free-space wavelength.

detector lengths of 100 and 250 μm . The optimal t_1 values are rounded to a tenth of a micrometer for realistic fabrication as well as to account for the relatively flat peaks of the curves shown in Fig. 5(a) and (b).

The total normalized power that is coupled into the photodetector layer $P_{\text{det}}/P_{\text{inc}} = P(z = L)/P_{\text{inc}}$ is also shown in Figs. 6 and 7 as a function of the detector length for optimal or nonoptimal t_1 separations for both TE₀ and TM₀ incident modes and for both $\lambda_0 = 1.3$ and 1.55 μm free-space wavelengths. Specifically, in Fig. 6(a), t_1 is selected to be either 0.3 μm (optimal value for TE₀ mode and $\lambda_0 = 1.3$) or 0.6 μm

(optimal value for TM₀ mode and $\lambda_0 = 1.3 \mu\text{m}$). Fig. 6(b) shows

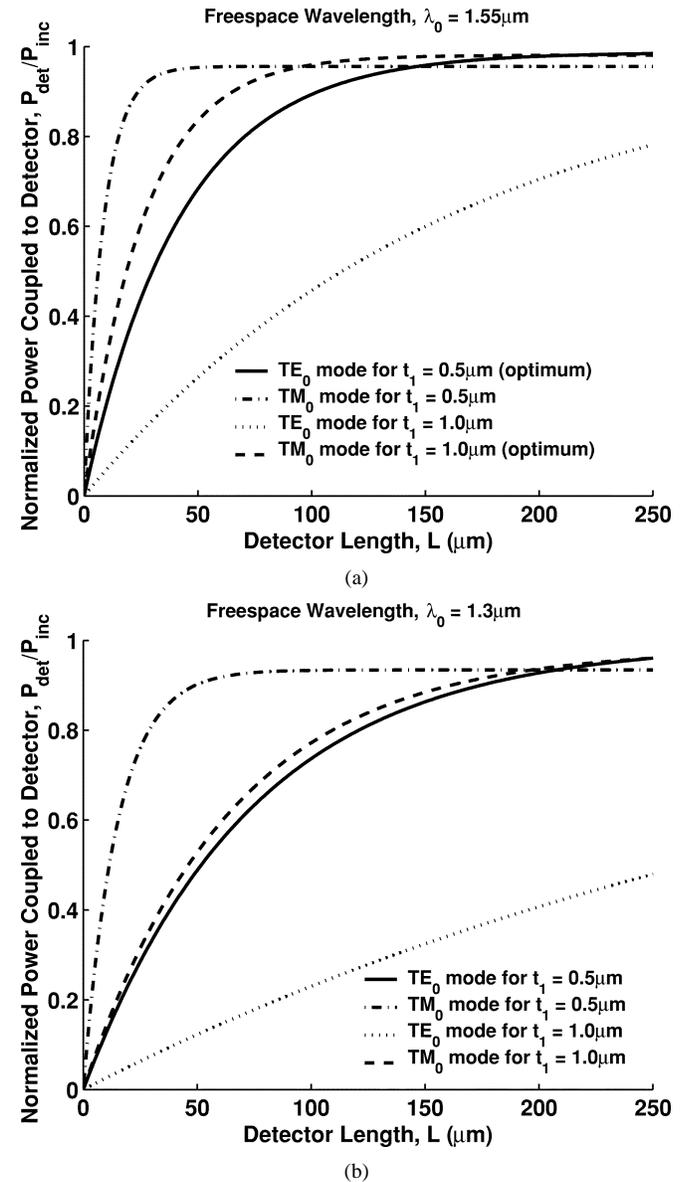


Fig. 7. Normalized power coupled to the detector $P_{\text{det}}/P_{\text{inc}} = P(z = L)/P_{\text{inc}}$ for the leaky waveguide formed in the region $z > 0$ as a function of the detector length for the case of the evanescent coupling architecture. The various line types show the normalized power $P_{\text{det}}/P_{\text{inc}}$ for both TE₀ and TM₀ incident modes as well as for optimal, near optimal, and nonoptimal t_1 separation. (a) For free-space wavelength $\lambda_0 = 1.55 \mu\text{m}$. For this wavelength the optimal t_1 values from Table I are as follows: for the TE₀ mode $t_1 = 0.5 \mu\text{m}$ and for the TM₀ mode $t_1 = 1.0 \mu\text{m}$. (b) For free-space wavelength $\lambda_0 = 1.3 \mu\text{m}$ using the optimal separations t_1 specified for the $\lambda_0 = 1.55 \mu\text{m}$ free-space wavelength.

the performance of the architecture for $\lambda_0 = 1.55 \mu\text{m}$ and for t_1 separations, which are optimal for the $\lambda_0 = 1.3 \mu\text{m}$ free-space wavelength. Similarly, in Fig. 7(a), t_1 is selected to be either 0.5 μm (optimal value for TE₀ mode and $\lambda_0 = 1.55$) or 1.0 μm (optimal value for TM₀ mode and $\lambda_0 = 1.55 \mu\text{m}$). Fig. 7(b) shows the performance of the architecture for $\lambda_0 = 1.3 \mu\text{m}$ and for t_1 separations, which are optimal for the $\lambda_0 = 1.55 \mu\text{m}$ free-space wavelength. From Figs. 6 and 7, it is deduced that

there is a possible selection of t_1 ($t_1 = 0.3 \mu\text{m}$) that makes the evanescent coupling efficient for both wavelengths and polarizations. In summary, the selection of the t_1 separation depends on the incident mode, the detector length, and the wavelength of operation. In addition, it can be seen that the percentage of the incident power that can be absorbed in the photodetector area can be as high as $\sim 98\%$.

B. Holographic-Grating Coupling From Waveguide to Substrate-Embedded Photodetector

In the case of the holographic-grating coupling architecture, the design of the grating is very important. The grating is designed in such a way that the first-order diffracted toward the photodetector region could be either normal or at a specified angle to the layer interfaces. Furthermore, the slanted grating configuration guarantees that a negligible amount of light will be diffracted into the cover direction due to its preferential diffraction properties. The grating design is based on the phase-matching conditions for the first diffracted order [23], [24]. If the desired order along the $-x$ direction forms an angle θ_s with respect to the $-x$ -axis, then the grating vector components K_x and K_z are given by

$$\beta - K_z = k_0 n_s \sin \theta_s \quad (9)$$

$$(\beta - K_z)^2 + K_x^2 = k_0^2 n_G^2 \quad (10)$$

where $\beta = k_0 N_{\text{eff}}$, with $k_0 = 2\pi/\lambda_0$, and N_{eff} is the effective index of the waveguide incident mode for $z < 0$. After K_x and K_z are defined, the period and the slant angle of the grating can be determined by the equations

$$\Lambda = \frac{2\pi}{(K_x^2 + K_z^2)^{\frac{1}{2}}} \quad (11)$$

$$\phi = \tan^{-1} \left(\frac{K_z}{K_x} \right). \quad (12)$$

In practice the angle $\theta_s = 0 \text{ deg}$, which means that the diffracted power is propagating along the $-x$ -axis.

Using the leaky-mode approach in conjunction with the rigorous coupled-wave analysis, the radiation coupling coefficient α can be calculated. The waveguide film layer thickness was selected again to be $t_2 = 1.0 \mu\text{m}$. The radiation coupling coefficient is shown as a function of the waveguide film layer and photodetector layer separation t_1 in Fig. 8(a) and (b) for both TE₀ and TM₀ incident polarizations and for both $\lambda_0 = 1.3$ and $1.55 \mu\text{m}$ free-space wavelengths. In these results, the effects of both the grating diffraction and the radiation of the waveguide mode due to the presence of the high-index photodetector layer are taken into account. It can be seen that, for $t_1 < 3 \mu\text{m}$, the evanescent coupling dominates the coupling process. However, as was mentioned previously, the evanescent coupling decreases exponentially with the distance t_1 . Therefore, for distances $t_1 > 3 \mu\text{m}$, the coupling process is due solely to the diffraction by the grating. This can be clearly seen in Fig. 8(b), where the radiation coupling coefficient oscillates as a function of t_1 . In this range of t_1 values, the effect of the evanescent coupling is negligible and the oscillations are due to Fabry–Perot multiple interference effects due to the changing t_1 distance. It is worth mentioning that the radiation coupling coefficient that

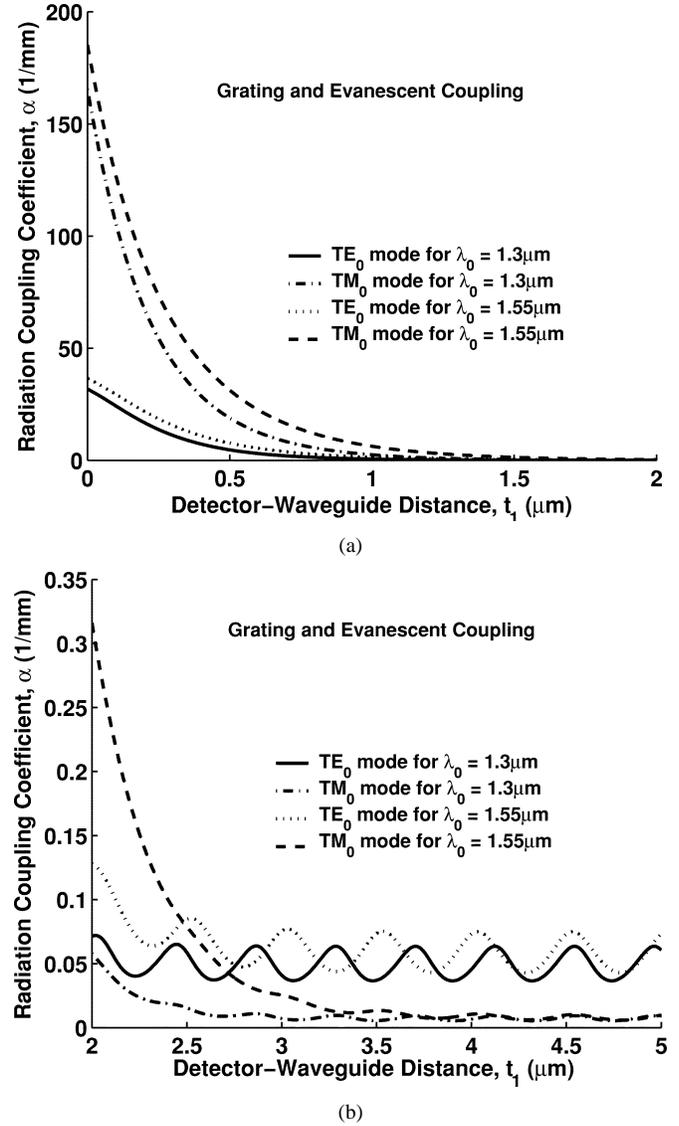


Fig. 8. Radiation coupling coefficient α for the leaky waveguide formed in the region $z > 0$ as a function of detector-waveguide (film) distance t_1 for the case of the holographic-grating coupler architecture. The various line types show the radiation coupling coefficient α for both TE₀ and TM₀ incident modes as well as for $\lambda_0 = 1.3$ and $1.55 \mu\text{m}$ free-space wavelengths. (a) The range of $t_1 = 0$ – $2 \mu\text{m}$, where the evanescent coupling dominates. (b) The range of $t_1 = 2$ – $5 \mu\text{m}$, where the holographic-grating coupling dominates.

is due to the grating diffraction alone is almost two to three orders of magnitude smaller than the radiation coupling coefficient that is due to the evanescent coupling alone. Therefore, the coupling of the grating for the parameters listed in this section is very small, making use of the grating inefficient since it would require detector layer lengths in the excess of $L = 1000 \mu\text{m}$ to achieve a $P_{\text{det}}/P_{\text{inc}} = P(z = L)/P_{\text{inc}}$ ratio on the order of 5–15%. This is mainly due to the tight confinement of the guided mode in the film region due to the high refractive index of the Ultem layer. If a smaller refractive index medium is selected, the grating can be much more effective, as will be shown in the case of the flip-chip-bonded-photodetector architecture.

Another important observation in the grating coupling architecture is that the radiation coupling coefficient of the TM polarization is much smaller than its TE polarization counterpart. This can be observed in Fig. 8(b). This effect is expected in

volume holograms and can be explained by the model of Kogelnik [30]. According to this simple two-coupled wave model when the angle between the incident and the diffracted wave is 90° , there is no coupling if the polarization is TM (electric field lying in the plane of incidence). In the waveguide film layer, the mode (incident field) is composed of two plane waves that form an angle (zigzag angle) near 90° with the boundary normal, thus resulting in nearly 90° separation between the incident and the diffracted fields (for a designed outcoupled angle $\theta_s = 0^\circ$).

C. Holographic-Grating Coupling From Waveguide to Flip-Chip-Bonded Photodetector

In the case of the holographic-grating coupling to flip-chip-bonded photodetector architecture, the design of the grating is similar to the previously examined case. The grating is designed in such a way that the first-order diffracted toward the photodetector region would be normal or at a specified angle to the layer interfaces. Furthermore, the slanted grating configuration guarantees that a negligible amount of light will be diffracted into the substrate direction. The grating design is based on the phase-matching conditions for the first diffracted order [23], [24]. If the desired order along the $+x$ -direction forms an angle θ_c with respect to the $+x$ -axis then the grating vector components K_x and K_z are given by

$$\beta - K_z = k_0 n_c \sin \theta_c \quad (13)$$

$$(\beta - K_z)^2 + K_x^2 = k_0^2 n_G^2 \quad (14)$$

where all parameters are defined as in the previous case. In practice the angle $\theta_c = 0^\circ$, which means that the diffracted power is propagating along the $+x$ -axis.

In this case, in order to increase the diffraction efficiency of the grating, a film layer of lower index (BCB of $n_f = 1.55$) was used in conjunction with a lower index substrate material (SiO_2 of $n_s = 1.45$). The film layer thickness was selected to be $t_2 = 0.6 \mu\text{m}$ that permits single-mode operation. The lower refractive index as well as the smaller film-layer thickness causes the guided mode to be less confined in the film layer. As a result, the optical field penetrates more into the grating region and consequently is more strongly diffracted. The separation between the photodetector and film layer was selected to be $t_1 > 3.5 \mu\text{m}$, so the effect of the evanescent coupling is negligible. Therefore, the radiation coupling coefficient that is determined using the rigorous coupled-wave analysis in conjunction with the leaky mode approach is due solely to the grating. The total normalized power [as determined by (6)] that is coupled into the flip-chip-bonded photodetector layer $P_{\text{det}}/P_{\text{inc}} = P(z = L)/P_{\text{inc}}$ is shown in Fig. 9 as a function of the detector length L for both TE_0 and TM_0 incident modes and for both $\lambda_0 = 1.3$ and $1.55 \mu\text{m}$ free-space wavelengths. As was expected for the wave diffracted normal to the boundary, the TM_0 case has very small radiation coupling coefficients, resulting in a very small amount of power that can be coupled via the grating. This effect is characteristic of the performance of volume gratings when the angle between the incident and the reflected wave is about 90° , as was discussed in the previous section. The percent of reflected power R was calculated by the FDFD method and was about 3.4% for TE polarization. The

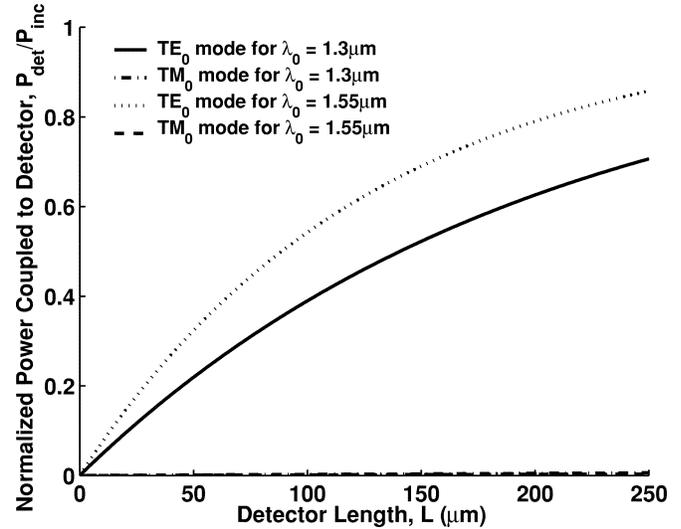


Fig. 9. Normalized power coupled to the detector $P_{\text{det}}/P_{\text{inc}} = P(z = L)/P_{\text{inc}}$ for the leaky waveguide formed in the region $z > 0$ as a function of the detector length for the case of the holographic-grating coupling with the flip-chip-bonded photodetector architecture. The various line types show the normalized power $P_{\text{det}}/P_{\text{inc}}$ for both TE_0 and TM_0 incident modes for $\lambda_0 = 1.3$ and $1.55 \mu\text{m}$.

preferential coupling efficiencies η_D were 98.99% and 99.89% for $\lambda_0 = 1.3$ and $1.55 \mu\text{m}$ free-space wavelengths for the TE polarization. The corresponding parameters for TM polarization were less than 50%, but this was due to the very inefficient diffraction process in the TM cases. For detector lengths up to $250 \mu\text{m}$, the percentage of the power that is coupled into the photodetector can be about 70–85%.

IV. FABRICATION ISSUES

One optical interconnection integration approach is to use embedded emitters/photodetectors, which have the optical signals originate and/or terminate in the waveguide directly on the board, without optical beam turning. Optical interconnections with integrated waveguides and optoelectronic (OE) devices in the substrate and epilayers have been reported in compound semiconductors [8], [9], [31]–[34], such as InP-based materials, with reported high coupling efficiency and monolithic integration. Polymer waveguides integrated onto Si [33] or GaAs [34], [35] electrical interconnection substrates that have photodetectors fabricated in the substrate, thus creating embedded waveguide interconnections, have been demonstrated. However, this approach does not accommodate noncompound semiconductor substrates, such as organic substrates. An embedded waveguide approach uses thin-film OE devices (with the OE device growth substrate removed), which can be bonded to any host substrate, including organic materials. The polymer waveguide material can then be deposited directly onto the thin-film active OE devices, which are thus embedded directly into the waveguide core, or embedded in the cladding.

This embedded optoelectronic waveguide interconnection technology for OE devices creates an optical interconnection option on the board/module/chip, which has exclusively electrical inputs and/or outputs (but can have optical inputs/outputs as well, if desired for line card to backplane perpendicular

interconnections, for example). Optical inputs that can be implemented for such planar interconnects include a coupled fiber, or embedded thin-film edge-emitting lasers (at wavelengths including 850, 980, 1300, and 1550 nm) that emit directly into the waveguide structure, for a source that originates on the board. Implementing these types of planar lightwave circuit (PLC) optical interconnections with embedded emitters and detectors may eliminate the need for optical beam-turning elements that route the beam perpendicular to the surface of the board/module/chip, and reduces waveguide to active OE device optical alignment to an OE device assembly step with sequentially aligned masking steps, which mirrors integrated circuit fabrication. In the future, the integration of additional PLC passive and further active embedded devices creates multiplexing and optical signal-processing options for more complex integrated optical/electrical microsystems, enabling the designer to choose functions from optical and electrical integrated “toolboxes” that offer the best of both integrated sets of functionality. The electrical interface circuits can be connected directly to the embedded active OE devices, through either wire bonding or bump bonding (as rising data rates preclude wire bonding), or through the electrical interconnection lines on the substrate. The assembly tradeoff that is inherent in the embedded optical waveguide interconnection is that the OE active devices are bonded directly to the substrate rather than bumped to the substrate. To minimize the impact of introducing optical interconnections into electrical interconnection substrates, the embedded OE waveguide interconnections can be integrated onto a fabricated electrical interconnection substrate through postprocessing. To enhance yield, at the board/module level, the optical interconnections can be electrically tested before the integrated circuits are assembled onto the board.

Independently optimized waveguides, embedded thin-film photodetectors, and a standard Si substrate (which can be used as an electrical interconnection substrate) have been integrated and tested [36]. Fig. 10(a) and (b) contains a schematic and a photomicrograph of a thin-film InGaAs-based inverted MSM photodetector bonded to pads with subsequent waveguide integration on top of the photodetector. Integration processes and measurement results are presented in the next section. Specifically, the integrated structure consists of a thin-film InP-based photodetector in a configuration of an Ultem (core)/BCB (clad) polymer waveguide integrated onto a Si interconnection substrate, with the photodetector integrated into the BCB cladding. The use of thin-film photodetectors (with the OE device growth substrate removed) enables the photodetectors to be bonded and electrically connected to the Si interconnection substrate and embedded in the polymer optical waveguides. Because the photodetector is embedded in substrate layer, the optical signal can be coupled from the waveguide into the photodetector without the use of beam turning elements. Using this heterogeneous integration technology, the thin-film OE devices, optical waveguides, and electrical interconnection media can be optimized separately for optimal mixed optical and electrical signal distribution for board-, module-, and chip-level interconnections.

In the cases where volume holographic gratings are needed, the holographic recording material used in this research is the DuPont OmniDex613 (HRF600X). This photosensitive

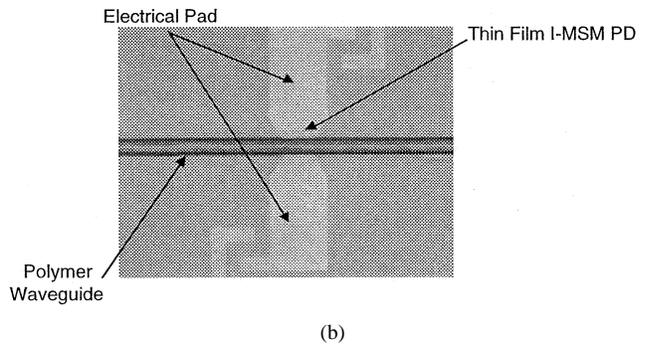
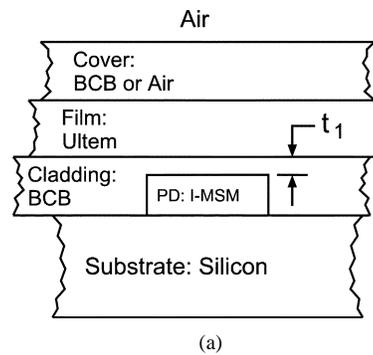


Fig. 10. (a) Cross-sectional view of the fabricated and tested samples. (b) Photomicrograph of a thin-film InP-based inverted-MSM photodetector bonded to electrical connection pads on a SiO_2/Si substrate. The photodetector is embedded in a BCB organic polymer waveguide structure, which was deposited onto the substrate/photodetector.

polymer is coated from a solution in an organic solvent onto a $50\text{-}\mu\text{m}$ -thick Mylar base with a removable $25\text{-}\mu\text{m}$ Mylar cover sheet. The film in which the grating on the waveguide can be recorded [as shown in Fig. 1(b) and (c)] is accomplished by means of cutting a piece out of a large sheet, removing the cover sheet, exposing it with the required interference pattern, and laminating it onto the desired surface. To record the slanted grating, high-index prisms should be used in order to achieve the required interference pattern within the photopolymer film layer. A two-beam interferometric configuration is used for the exposure in conjunction with an Ar-ion ultraviolet wavelength of 363.8 nm . The optimal recording conditions to obtain high diffraction efficiency grating couplers can be determined [37], [38]; they depend on the exposure intensity, exposure dosage, and postbaking after exposure. After the grating is recorded, it can be laminated onto the waveguide; then the Mylar layer can be removed. This summarizes the procedure for obtaining the gratings shown in architectures of Fig. 1(b) and (c).

V. COMPARISON OF THEORY AND EXPERIMENT

In this section, the presented analysis and experimental results are compared in the case of evanescent coupling from waveguide to substrate-embedded photodetector. Two samples have been fabricated and tested. The sample configurations fall under the general structure shown in Fig. 1(a). A more detailed configuration of the fabricated devices is shown in Fig. 10(a), and a microphotograph is shown in Fig. 10(b). Sample no. 1 is composed of an air cover, an overcladding BCB layer of thickness of $2.0\text{ }\mu\text{m}$, an Ultem film layer of thickness of $1.0\text{ }\mu\text{m}$, a BCB under cladding of thickness $\sim 1\text{ }\mu\text{m}$ (on top of the

TABLE II
COMPARISON OF THEORETICAL COUPLING EFFICIENCIES $P_{\text{det}}/P_{\text{inc}}$ TO
EXPERIMENTALLY OBTAINED ONES FOR THE CASE OF THE EVANESCENT
COUPLING FROM WAVEGUIDE TO SUBSTRATE-EMBEDDED PHOTODETECTOR

Sample No. 1				
Distance t_1 (μm)	Analytical $P_{\text{det}}/P_{\text{inc}}$			Measured $P_{\text{det}}/P_{\text{inc}}$ (%)
	TE Pol. (%)	TM Pol. (%)	Avg. (%)	
0.8	6.33	22.68	14.51	11.83
1.0	2.73	10.70	6.72	—
1.2	1.18	4.87	3.03	—

Sample No. 2				
Distance t_1 (μm)	Analytical $P_{\text{det}}/P_{\text{inc}}$			Measured $P_{\text{det}}/P_{\text{inc}}$ (%)
	TE Pol. (%)	TM Pol. (%)	Avg. (%)	
0.2	30.01	65.97	47.99	—
0.4	14.63	42.47	28.55	—
0.6	6.10	21.09	13.60	9.39

photodetector), and the embedded in the undercladding I-MSM InP-based photodetector. The structure is on top of a silicon microelectronic substrate. Sample no. 2 is composed of an air cover (overcladding), an Ultem film layer of thickness of 1.8 μm , and a BCB under cladding of thickness $\sim 0.2 \mu\text{m}$ (on top of the photodetector). Again the I-MSM InP-based photodetector is embedded in the BCB under cladding. As in the first sample, the structure has been grown on top of a silicon microelectronics substrate. Details about the fabrication process can be found in [36]. For both samples, the testing was done using a laser diode of 1.3 μm free-space wavelength coupled into a multi-mode fiber. Also for both samples, the photodetector length was $L = 150 \mu\text{m}$. Light from the end of the fiber was focused on the polished edge of the film layer of the waveguide structure for both samples, and sufficient coupling was achieved. The dark current and the responsivity of the I-MSM photodetector were measured before and after the waveguide fabrication. The dark current varied depending on the applied voltage between 0.1–50 nA. The responsivity was measured to be 0.4 A/W at 5 V. More details about these can be found in [36].

The experimental coupling efficiency of the light that was evanescently coupled from the waveguide into the embedded photodetector was estimated by measuring the photocurrent and knowing the responsivity of the photodetector. The amount of input power was estimated theoretically using a finite-difference beam-propagation method. Therefore, the experimentally obtained values of the coupling efficiencies are shown in Table II (as measured $P_{\text{det}}/P_{\text{inc}}$) for both samples. Variation in the photodetector and the BCB under cladding thicknesses make the actual knowledge of the separation t_1 between the photodetector and the film waveguide layer [see Figs. (1a) and (10a)] uncertain within fractions of a micrometer. The coupling efficiency $P_{\text{det}}/P_{\text{inc}}$ depends strongly on the separation distance t_1 , as can be seen in Fig. 5(a) and (b). Therefore, in order to compare the present analysis with the experimentally obtained results, the separation t_1 was varied by a few tenths of a micrometer to accommodate the uncertainty of the actual separation t_1 . Both the theoretical and experimental results are shown in Table II. During the experiment, it was known that the input light was not polarized. Therefore, in Table II, both the TE and TM polarization results are shown, as well as their average (assuming equal

amount of TE and TM light). From the theoretical results, it can be observed that the actual waveguide-film/photodetector separation t_1 was near 0.8 and 0.6 μm for samples 1 and 2, respectively, which is well within the range of uncertainty of t_1 . The experimental measurements were slightly lower than the theoretical results since the scattering losses were not considered in the analysis.

VI. SUMMARY AND CONCLUSIONS

In this paper, potentially low-cost fully substrate-embedded or flip-chip-bonded optical interconnect architectures have been analyzed and compared. The architectures involve a volume-holographic grating coupling for beam turning and/or an embedded thin-film inverted-MSM photodetector for evanescent coupling. The architectures can be integrated onto silicon microelectronic substrates with InP-material-based thin-film photodetectors and optical quality polymer layers that can be used as waveguides and/or volume holographic gratings. Similar architectures can be implemented on low-cost organic substrates such as FR4 epoxy without any significant theoretical modifications. Three architectures have been investigated as follows: a) an evanescent-coupling architecture with a substrate-embedded photodetector, b) a volume-holographic-grating coupler architecture with a substrate-embedded photodetector, and c) a volume-holographic-grating coupler architecture with a flip-chip-bonded photodetector.

It has been found that the evanescent-coupling architecture can be very efficient for both polarizations (TE and TM) provided that the distance between the waveguide film layer and the photodetector layer [t_1 in Fig. 1(a)] is small compared to the free-space wavelength. In this case, power from the waveguide is radiated and absorbed into the photodetector. However, as distance t_1 increases, the radiation coupling coefficient decreases exponentially. Furthermore, the evanescent-coupling architecture is not in general very wavelength-sensitive. On the other hand, the architectures that involve a volume holographic grating can be useful either when the distance t_1 is large or when there is a need for wavelength/polarization sensitivity [in the case of the architecture with a substrate-embedded photodetector shown in Fig. 1(b)]. In the case of the architecture with the flip-chip-bonded photodetector [Fig. 1(c)], the grating is absolutely necessary since the separation between the waveguide and the photodetector is large and no evanescent coupling can occur. In the latter case, slanted volume gratings offer the advantages of alignment insensitivity as well as preferential coupling. However, for normal outcoupling, the volume holographic grating is efficient in the case of TE polarization but very inefficient in the case of TM polarization. If the desired direction of the out-coupled power is about 45° instead of normal to the interfaces, then both TE and TM polarizations can become equally efficient [24]. Furthermore, the grating coupling architectures can become more efficient if the waveguide/grating combination is designed in such a way that the optical mode extends well into the grating region, thus enhancing the interaction between the guided mode and the grating.

In addition, some of the fabrication issues for low-cost implementations of the abovementioned architectures have

been discussed. Architectures involving evanescent coupling with substrate-embedded photodetectors have already been implemented [36], while architectures involving volume holographic gratings are currently under investigation.

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