



*Single Operator Control of Autonomous Multi-Vehicle Swarms*  
*Post-Scenario Questionnaire*

3.2 **Tactic:** In your recollection, what would best describe the tactic you used to finish your task?

- (1) Place secondary UAVs to create R/F coverage to and around the target and then (2) use a *yet unused* UAV as the primary vehicle to complete the inspection task.
- (1) Select a primary UAV and move it towards the target and (2) deploy secondary UAV when necessary to increase the R/F coverage from the GCS to the target.
- (1) Build up R/F coverage to and around the target and then (2) use *already deployed* UAVs one after the other as the primary UAV to inspect the target.
- Other:** Please describe briefly how you approached your mission in the textbox in question 3.4.

3.3 **Hindsight:** Would you say that the final R/F coverage of your secondary UAVs turned out to be roughly how you anticipated it to be before you started moving UAVs?

- Agreed: Yes, the secondary UAVs roughly provided coverage where I initially thought it would end up being.
- Disagreed: The R/F coverage provided by the secondary UAVs didn't end up matching my expectations.
- Not Applicable: I didn't think about where and how the UAVs would provide coverage, I just started moving them and reacted to how the coverage was build up.

3.4 If you answered *Other* in question 3.2 please describe briefly (and legibly) how you approached your mission.

## 4 Performance

4.1 Scenario

- a1    a2    a3    a4    A1    A2    A3    A4

Time:

